MULTIPHYSICS COMPUTATIONAL MODELING OF PHOTOMECHANICAL EFFECTS DURING INFRARED NEURAL STIMULATION

By

Mayna Hatram Nguyen

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Approved:

E. Duco Jansen, Ph.D.

Anita Mahadevan-Jansen, Ph.D.

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CHAPTER 1 Introduction

1.1 Optical Neural Modulation

It is estimated that more than 600 diseases affect the nervous system, with 9 million deaths and 276 million disabilities that occurred from neurological disorders worldwide in 2016¹. Interfacing with the nervous system can be done with neuromodulation, which involves stimulating or blocking action potentials in the nervous system. Neuromodulation has three main applications: prosthetics to improve motor or cognitive neural function (including cochlear implants), therapy to treat neural diseases such as epilepsy, Parkinson's disease, depression, and traumatic brain injury, and neuroscience research to investigate the function of neurons and neural networks². The current gold standard for neuromodulation is electrical stimulation, which is used clinically in deep brain stimulation, pacemakers, and other neuromodulation devices³. During electrical stimulation, electrodes are placed on the target neuron or nerve to apply a potential gradient². However, this method of stimulation has limitations, such as the need for direct contact, the cause of a stimulation artifact, MRI incompatibility, and electrode complications⁴⁻⁶. In addition, spatial selectivity in electrical stimulation is also severely limited by current spread, which is an issue in the clinic as there is a need to target specific areas in the brain or fibers in the nervous system without affecting nearby areas. Consequently, there is a need for an alternate method of neuromodulation that overcomes these limitations.

Optogenetics has become a popular tool for optical neuromodulation since 2005, when Boyden *et al.* discovered that pulses of blue light elicited depolarizing spike trains in neurons expressing a microbial opsin gene, Channelrhodopsin-2. This discovery showed a promising way to precisely control neuronal activity with specific targeting of cells⁷. Opsins act as light-activated ion channels, allowing for quick and precise optical manipulation of biological processes². Since 2005, several opsins have been discovered to be activated or inhibited by different wavelengths of light, with the three major classes of microbial proteins used for single-component optogenetics being bacteriorhodopsins, halorhodopsins (inhibitory), and channelrhodopsins⁸. However, one major drawback of optogenetics for human clinical use is that it requires genetic modification, which is challenging for clinical translation as it raises safety and ethical concerns.

Another emerging technique for neuromodulation is focused ultrasound. This non-invasive technique delivers mechanical forces to cells deep in tissue using pressure waves, which can be focused using interference of the incident waves. Despite ultrasound being able to evoke a response in both the central and peripheral nervous systems in several neuronal targets⁹, the underlying mechanism is mostly unknown due to the multiple physical effects that occur. Recently it was shown that ultrasound produces a mechanical force, which results in extracellular calcium entering the cell through the activation of mechanosensitive channels. This calcium influx depolarizes the cell membrane and opens voltage-gated ion channels and stimulation. While a significant step towards understanding the mechanism has been made, more work is needed to further look at the precise forces caused by ultrasound and the specific roles of different mechanosensitive ion channels¹⁰. Moreover, there is also evidence that absorption or dissipation of the mechanical (kinetic) energy in ultrasound waves in tissue leads to local temperature increases and therefore a thermal component of ultrasound neuromodulation cannot be excluded^{9,10}.

1.2 Infrared Neural Stimulation

Another optical neuromodulation method, infrared neural stimulation (INS), emerged in 2005 when Wells *et al.* demonstrated the use of pulsed infrared light (λ =2.1-6.1 µm) to excite action potentials in *in vivo* rat sciatic nerves. A free-electron laser (FEL) was used for the initial studies, where it was shown that the radiant exposure threshold to evoke INS followed the water absorption curve, suggesting that the mechanism is likely to be primarily photothermal driven by water absorption. It was also shown that the optimal wavelengths for stimulation occurred at relative valleys in the water absorption curve, with ablation damage occurring at 2.5 times the stimulation threshold, suggesting that optical stimulation is a safe technique to modulate nerves^{11,12}. INS was shown to be spatially selective (Figure 1.1), artifact-free, contact-free, and does not require genetic modification or exogenous compounds, and therefore overcomes many of the limitations of electrical stimulation¹³. Since its discovery, multiple studies have demonstrated the use of INS to modulate neural activity *in vitro* and in animal models such as *Aplysia* nerve, rat sciatic nerve, musk shrew vagus nerve, gerbil and cat auditory nerves, quail embryo hearts, non-human primate cortex, and even in dorsal roots in humans^{13–18}.



Figure 1.1 Infrared Neural Stimulation provides spatially selective targeting of nerves (a) Threshold compound muscle action potential (CMAP) response from electrical stimulation of the main branch of the rat sciatic nerve proximal to the first branch point (b) Corresponding results from threshold optical stimulation of specific target nerve fibers that innervates the gastrocnemius with no response from adjacent nerve fibers (quiet biceps femoris), showing selective optical stimulation. Figure from Wells *et al.* used with permission from Elsevier¹³.

Wells *et al.* were also the first to look at the mechanism of INS. It was found that the laser energy is absorbed by chromophores in the tissue and is converted into a spatio-temporal thermal gradient which results in the excitation of the target cells¹⁹. Shapiro *et al.* investigated the mechanism of INS by recording currents of oocytes, human embryonic kidney cells, and lipid bilayers as they were stimulated with an infrared laser pulse. It was shown that the currents followed the temperature profiles, which consisted of a sharp rise followed by an exponential decay, confirming that INS does involve a temperature gradient. Furthermore, observing no change in current when adding or removing voltage-gated channels and blocking ion channels suggested that INS works on the most basic lipid bilayer, not just excitable cells. Experimental evidence of a transient change in membrane capacitance was also measured. The capacitance was further investigated by developing a model based on the classical Gouy-Chapman-Stern theory of doublelayer capacitors^{20,21}. This model was later revised by Plaksin *et al.* to account for a modeling sign error²² and thermally induced membrane deformations that were inferred from small-angle x-ray and neutron scattering measurements and molecular dynamics simulations. Overall, it was shown that there is a temperature-induced membrane capacitance increase of 0.3%/°C specifically due to the phospholipid bilayer membrane thinning axially and expanding laterally (Figure 1.2), which agrees with the experimental capacitance change that Shapiro *et al.* found. The observation of depolarization driven by a membrane capacitance change is a fundamental discovery toward understanding the INS mechanism. However, capacitance is unlikely to be the sole mechanism because the capacitance threshold needed to generate an action potential is higher than what Shapiro *et al.* and Plaksin *et al.* found²³.



Figure 1.2 Capacitance increase due to changes in the bilayer lipid membrane. (a) Modeling and experimental results showing a 0.3%/°C increase in capacitance due to (b) the membrane decreasing in thickness and increasing in surface area from a temperature rise. Figure from Plaksin *et al.*²¹ licensed under CC BY 4.0.

After Shapiro *et al.* looked at the membrane capacitance as a part of the mechanism, it was hypothesized that the thermal gradient destabilizes phospholipids in the membrane, causing

nanopores to form and allowing extracellular ions to flow in and depolarize the cell. Using fluorescent markers YO-PRO-1 and propidium, it was shown that impermeant cell ions were able to leak into the cell, suggesting that 1-2 nm transient pores were created. In addition, rapid transient increases in intracellular calcium were measured in primary hippocampal neurons, suggesting a depolarization due to nanopore formation. Nanopores are more likely to be formed when the lipid bilayer is in a phase transition, which is dependent on thermodynamic properties, including pressure and temperature. Thus, it is hypothesized that the membrane properties are altered by pressure, temperature, or a combination of the two²⁴.

Transient receptor potential vanilloid (TRPV) channels have been hypothesized to play a role in INS, but details remain unclear. A thermal gradient and not absolute temperature appears to drive stimulation¹⁹, so TRPV channels would not be implicated since they activate at an absolute temperature threshold. However, some studies that used channel blockers have shown evidence that TRPV channels are involved. In a pharmacological study, TRPV4 channels were proven to play a role in laser-evoked responses in sensory neurons²⁵. Other studies implicated TRPV1 as responsible for stimulation in both rat vagus nerves and mice auditory nerves^{26,27}. While it appears that the INS mechanism has a photothermal component, more work is needed to determine what exactly drives INS, both biophysically and what the underlying neural effects are from the biophysics.

Laser-induced stress and volumetric thermal expansion have previously been considered as the mechanism, but the conclusions from the experimental results dismissed a photomechanical contribution to the mechanism¹⁹. Since then, supporting evidence of a mechanical component to the mechanism has been more apparent with different stimulation thresholds at shorter pulses^{20,28,29} and a possible mechanical mechanism in cochlear stimulation^{30–32}. Additionally, various mechanosensitive channels have been investigated for ultrasound stimulation. Yoo *et al.* found that in cortical neurons, mechanosensitive channels TRPP1/2, TRPC1, and Piezo1 respond to mechanical interactions, which then opens TRPM4 channels and causes depolarization¹⁰. TRAAK K⁺ channels in Xenopus oocytes were found to be sensitive to pressure (-15mmHg = -2000Pa), which caused channel opening due to membrane tension ³³. Piezo2 was observed to be essential for mechanical firing in a subset of mouse sensory neurons³⁴. Kubanek *et al.* showed that focused ultrasound modulates K⁺ and Na⁺

currents through K2P and Nav1.5 channels³⁵. Based on these findings, a mechanical component could potentially be involved in the INS mechanism.

1.3 Computational Modeling of Laser Tissue Interactions

1.3.1 Optical Interactions

As laser light irradiates tissue, specific interactions occur based on the tissue optical properties. At the surface, some light undergoes reflection while the remaining light refracts based on the angle of incidence and refraction index of the tissue. Some light gets absorbed, where it is converted into heat, and the remaining light scatters and propagates through the tissue. The radiative transport equation describes the transfer of energy through a medium and is written as:

$$\frac{dL(r,\hat{s})}{ds} = \mu_a L(r,\hat{s}) - \mu_s L(r,\hat{s}) + \int_0^{4\pi} p(\hat{s},\hat{s}') L(r,\hat{s}) d\omega' + S(r,\hat{s})$$

where L [W/m² · sr] is the radiance, μ_a [1/m] is the absorption coefficient, μ_s [1/m] is the scattering coefficient, p is the scattering phase function [1/sr], and S is the optical source generated at r in direction s ³⁶. However, the radiative transport equation cannot easily be solved in the closed form. Therefore, approximations and stochastic methods, such as Monte Carlo simulations, have been used to approximate the solution to modeling light transport in tissue.

Monte Carlo is a statistical method that uses random sampling of variables from probability distributions. Monte Carlo for light transport in biological tissue was first implemented in 1983 by Adams and Wilson³⁷. Since then, Prahl *et al.* introduced the inclusion of boundary conditions and anisotropic scattering in 1989³⁸, and the first open-source multilayer Monte Carlo simulator MCML was developed by Wang and Jacques in 1995³⁹. Recently, Monte Carlo has evolved to be GPU-accelerated and in-browser with the development of MCX Cloud^{40,41}. The process of using Monte Carlo for light propagation starts by initializing photons with a weight of 1. The step size s is determined by randomly sampling the photon's free path based on the absorption and scattering coefficients, which add to form the total attenuation coefficient μ_t [1/m]. With ζ as a random number between 0 and 1, the step size is calculated as:

$$s = \frac{-\ln\left(\zeta\right)}{\mu_t}$$

The photon is then moved the step size s and a portion of the photon weight is deposited. The amount of deposited weight is stored in the corresponding position and is calculated by:

$$\Delta W = W \frac{\mu_a}{\mu_t}$$

If the photon's weight falls below some threshold value the photon is terminated. A roulette technique is used to determine if a photon should be terminated. This technique allows for energy conservation by only terminating photons with weight w a chosen fraction of the time (1 in m chance), and the remaining photon has an increased weight mw to allow it to continue to propagate. Otherwise, the photon is scattered based on the deflection angle θ and the azimuthal angle ψ . The deflection angle is based on the anisotropy g, which indicates forward scattering with a value close to 1 or backward scattering with a value close to -1, and the Henyey-Greenstein probability density function for scattering. The scattering angle is calculated as:

$$\cos(\theta) = \frac{1 + g^2 - (\frac{1 - g^2}{1 - g + 2g\zeta})^2}{2g}$$

Where ζ is a random number between 0 and 1. If there is isotropic scattering (g = 0), then the angle is calculated as:

$$\cos(\theta) = 2\zeta - 1$$

And the azimuthal angle is calculated as:

$$\psi = 2\pi\zeta$$

Where ζ is a random number uniformly distributed between 0 and 1. When a photon encounters a boundary, the photon is either reflected or transmitted. To handle a boundary, a fraction of the photon escapes as reflectance (if at the surface) or transmittance (if at the bottom), and the remaining photon weight is internally reflected into the tissue to continue propagating³⁶. Ultimately, Monte Carlo simulations compute the spatial distribution of absorbed photons and thus the heat source S(r,z) for a 2D distribution or S(x,y,z) for a 3D distribution. A 2D distribution is useful for symmetric, radial problems, while 3D distributions are needed for asymmetric problems.

1.3.2 Photothermal interactions

When laser light is absorbed in tissue, this results in a thermal energy that is deposited in the tissue. The local temperature rise at a given point at the end of a short, thermally confined laser pulse with a pulse duration of Δt can be estimated as:

$$\Delta T(x, y, z) = \frac{\mu_a \phi(x, y, z) \Delta t}{\rho c}$$

where μ_a is the absorption coefficient [1/m], ϕ is the fluence rate [W/m²], ρ is the density [kg/m³], and c is the specific heat capacity [J/kg·K]³⁶. Heat transfer in tissue mainly occurs due to conduction, when heat is transferred due to a temperature gradient or driving force.

The Fourier heat equation is typically applied to calculate how temperature varies with space and time and is determined by the thermal conductivity κ [W/m·K]:

$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (\kappa \nabla T)$$

Computational modeling of heat transfer in tissue follows the traditional Pennes bioheat equation^{36,42} since this takes into account the thermal interaction of tissues with blood perfusion:

$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (\kappa \nabla T) + \omega p_b c_b (T_b - T) + \dot{Q}_{met}$$

where ρ is density [kg/m³], c is specific heat capacity [J/kg·K], κ is thermal conductivity [W/m·K], ω is the perfusion coefficient [1/s], and ρ_b , c_b , and T_b are the density, specific heat, and temperature, respectively of the perfusive medium. \dot{Q}_{met} is the heat generated from metabolism. To account for the heat from the laser source \dot{Q}_{source} [W/m³], the equation is modified to:

$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (\kappa \nabla T) + \omega p_b c_b (T_b - T) + \dot{Q}_{met} + \dot{Q}_{source}$$

A convective boundary condition occurs at the surface of a tissue, which in our case, is a nerve exposed to air. Convection involves a heat exchange between a solid at a different temperature from flowing air or fluid. Newton's law of cooling describes this convective flow \dot{Q}_s [W] as:

$$\dot{Q}_s = hA(T_\infty - T_s)$$

where h is the convective coefficient $[W/m^2 \cdot K]$, A as the interface area, and the temperature of the surface T_s and bulk fluid $T_{\infty} [K]^{36}$. Solutions to determine the temperature distribution over time from laser irradiation typically involve modeling schemes such as finite-difference or finite-element modeling⁴³⁻⁴⁵ and have been implemented for many years.

1.3.3 Photomechanical interactions

Photomechanical interactions are mostly known to occur through the explosive vaporization of tissue during ablation or the direct generation of pressure waves, but other mechanical effects such as surface displacement from volumetric expansion can also be observed. Pressure waves can be generated in three ways, thermoelastic expansion from the heating of tissue by a pulsed laser, material recoil caused by ablation, or the collapse of vapor cavitations. Due to our application of INS, which uses relatively low radiant exposures (well below the ablation threshold), this thesis will focus on generating pressure waves from thermoelastic expansion as well as surface displacement from volumetric expansion. Thermoelastic expansion typically requires stress confinement, which is when the duration of the laser pulse is shorter than the stress confinement time τ_{str} , which is the time it takes for the pressure to diffuse out of the irradiated volume and is calculated by:

$$\tau_{str} = \frac{\delta}{\sigma}$$

Where δ is the penetration depth of the tissue [m] and σ is the speed of sound in tissue (1500 m/s) ³⁶.

In Figure 1.3, the confinement zones are shown for different pulse durations and penetration depths.



Figure 1.3 Stress and thermal confinement zones shown as a function of penetration depth and pulse duration. Stars indicate typical INS pulse durations and the corresponding penetration depth for $\lambda = 1470$ nm and 2120nm. Adapted from Jacques 1993⁴⁶.

Typical INS parameters include using lasers in the IR range that are near a water absorption peak, such as a Ho:YAG laser at 2120 nm. Previous pulse durations have included a 350 μ s pulse and a 2 ms pulse from a 1470nm diode laser with a similar absorption coefficient. These pulses are clearly thermally confined. However, the Ho:YAG 350 μ s pulse has a 1 μ s spike at the beginning of the pulse²⁸, which is much closer to stress confinement, so mechanical effects such as pressure waves from thermoelastic expansion are possible, even if small. The pressure can be related to the thermal expansion by the Grüneisen parameter Γ , which is the conversion efficiency from thermal to mechanical energy. The equation describing the pressure increase ΔP is:

$$\Delta P(z) = \Gamma \mu_a H(z)$$

Where H(z) is the depth-dependent fluence distribution $[J/m^2]^{36}$.

1.3.4 SESE Model

The Scalable Effects Simulation Environment (SESE) is a computer program developed for the Air Force Research Laboratory by Nanohmics (Austin, TX) that combines an optical, thermal, and mechanical model to simulate the physical effects of materials due to laser irradiation (Figure 1.4). Full details of SESE can be found in the publicly available technical report⁴⁷, but the model components are described briefly here.



Figure 1.4 Overview of SESE Model showing the optical, thermal, and mechanical components, inputs, and outputs.

The optical component utilizes a Monte Carlo propagation technique with ray tracing to simulate absorption, scattering, reflection, and refraction. The temperature distribution is calculated using a finite-volume discretization and a red-black successive over-relaxation (RBSOR) method to solve the heat equation with the benefits of rapid convergence and parallelization⁴⁸. SESE v.2.6.0 includes the addition of the capability to model photoacoustic effects. A finite-difference time-domain method is used to solve the linear-elastic wave equation, which couples to the photothermal solver with a source term that accounts for the thermal

expansion of the material. SESE also has the capability to determine thermal and chemical damage, but this is out of the scope of this thesis. SESE's photoacoustic approach is summarized as follows, with the variables defined in Table 1.1.

Starting with an equivalent of Newton's second law of motion, a momentum density is related to a force density generated by the stress tensor:

$$\rho \dot{\mathbf{v}} = \nabla \cdot \sigma + f$$

This is then integrated to get v, the displacement velocity, and again to obtain \dot{u} , the displacement:

$$v = \dot{u}$$

From v, the strain rate $\dot{\varepsilon}$ is calculated:

$$\dot{\varepsilon} = S : (\nabla \mathbf{v})$$

Lastly, the stress tensor is calculated by integrating:

$$\dot{\sigma} = \lambda I \left(I : \dot{\varepsilon} \right) + 2\mu \dot{\varepsilon} - \alpha v \left(\lambda + \frac{2}{3} \mu \right) \dot{w} I$$

Parameter	Symbol	Units
Density	ρ	kg/m ³
Force density	f	N/m ³
Displacement velocity	V	m/s
Displacement	ù	m
Strain rate	Ė	
Symmetrization operator	S	
Stress tensor	σ	Pa
Elastic modulus	λ	Pa
Rank 2 identity tensor	Ι	
Shear modulus	μ	Pa
Thermal expansion coefficient	α_v	1/K
Temperature rate	Ŵ	

Table 1.1 Summary	' of	variables	used in	SESE	mechanical	model
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For visualization of the simulation results, ParaView was used to analyze model outputs in 3D space over time and to extract data as needed. The work in this thesis focuses on using SESE as it provides a combined optical, thermal, and mechanical model for laser irradiation and allows for flexible geometries with various and tunable material properties.

Computational models provide valuable insights into the physical processes that are on the microscopic scale and are difficult to determine experimentally. Therefore, the model should be validated before employing SESE as a tool to ensure accurate results. For each of the optical, thermal, and mechanical components, SESE has been verified against analytical solutions and other models⁴⁷. Additionally, SESE has been validated against experimental skin damage thresholds for the thermal model^{49,50}. Since the photoacoustic model in SESE is a recent addition, experimental validation has yet to be published but is addressed in Chapter 2 of this thesis.

Based on the potential involvement of mechanosensitive ion channels, evidence of a photomechanical mechanism in cochlear stimulation, and the fact that shorter pulses are closer to stress confinement than longer pulses, we hypothesize that a mechanical component is involved in shorter pulses that results in more efficient stimulation. Using computational modeling, we can obtain an understanding of the underlying biophysics during an infrared pulse on an incident nerve. This thesis aims to use and validate an optical-thermal-mechanical computational model to investigate mechanical effects in peripheral nerve INS. The transient pressure waves and displacement modeling results will be compared to experimental stimulation thresholds at different pulse widths to gain insight into a potential mechanical component that is involved in the INS mechanism.

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CHAPTER 2 Multiphysics computational modeling of photomechanical effects during infrared neural stimulation

2.1 Introduction

Infrared Neural Stimulation (INS) is a technique that uses pulsed infrared light to excite action potentials in neural tissue. The initial INS studies utilized a free-electron laser (FEL) and suggested a photothermal mechanism where the laser energy is absorbed by chromophores in the tissue and is converted into thermal energy which results in the excitation of the target cells. Unlike traditional electrical stimulation, INS has unique characteristics such as being spatially selective, contact-free, and not having the large stimulation artifact that electrical stimulation has^{1,2}. Since its discovery, multiple studies have demonstrated the use of INS to modulate neural activity *in vitro* and in animal models such as *Aplysia* nerve, rat sciatic nerve, musk shrew vagus nerve, gerbil and cat auditory nerves, quail embryo hearts, non-human primate cortex, and even in dorsal roots in humans^{3–8}.

Despite INS being used effectively in several applications, there is currently an incomplete picture of the underlying biophysical mechanism(s). It is well established that INS is strongly dependent on the spatial and temporal thermal gradients from laser irradiation⁹. However, it is unknown if other contributions have a significant role in the overall mechanism. Previous work from Shapiro *et al.* and Plaksin *et al.* showed a temperature-induced membrane capacitance increase specifically due to the phospholipid bilayer membrane thinning axially and expanding laterally^{10,11}. However, a computational model developed by Peterson *et al.* indicated that capacitance is unlikely the sole mechanism because the capacitance change needed to generate an action potential is higher than what Shapiro *et al.* measured in lipid membranes^{10,12}. Thermally activated Transient Receptor Potential Vanilloid (TRPV) channels have also been suggested as part of the mechanism. A TRPV blocker eliminated the action potential response from 1875 nm stimulation in retinal and vestibular ganglion cells, suggesting that TRPV channels are involved in the neural response of these neurons. Specifically, TRPV4 channels activated from heat led to an influx of calcium ions¹³. In cochlear stimulation, TRPV1 channels were shown to be important as most mice that lacked TRPV1 channels could not evoke action

potentials on the auditory nerve when stimulated optically¹⁴. By using capaszepine as a channel blocker in rat vagus nerves, TRPV1 was implied to be responsible for an increase in intracellular Ca²⁺ concentration¹⁵. Additionally, intracellular Ca²⁺ responses have shown to be induced by INS in *in vivo* rat somatosensory cortex¹⁶, NG108 cells, CHO-K1 cells¹⁷, neonatal cardiomyocytes¹⁸, and *in vivo* mouse cortical neurons¹⁹. These studies have made significant progress toward uncovering the mechanism, but more work is still needed to fully understand how INS works biophysically.

Several studies have hypothesized that INS involves a photomechanical mechanism with shorter pulse widths. In a recent study by Throckmorton et al., different laser parameters of INS for rat sciatic nerve were compared. It was shown that a diode laser with a pulse width of 350 µs was not significantly different from a diode laser with a pulse width of 2 ms (Figure 2.1(a)). More interestingly, a Ho:YAG laser had a lower stimulation threshold than a diode laser with the same pulse duration of 350 µs and similar absorption coefficient (Figure 2.1(b)). Taking a closer look into the pulse structure of the lasers, the Ho:YAG laser has a large ~1 µs spike at the beginning of the pulse containing roughly 10% of the laser energy²⁰. Removing the spike from the Ho:YAG pulse resulted in a higher stimulation threshold than the native Ho:YAG pulse, indicating the spike is likely responsible for the superior stimulation efficacy. When looking at stress vs. thermal confinement zones²¹, a 1 μ s pulse is much closer to stress confinement (calculated $\tau_{str} = \delta/\sigma = 220$ ns for $\lambda = 2120$ nm) than the longer 350 µs pulse duration, supporting the idea of a mechanical component being the driving force behind the lower stimulation threshold. Furthermore, Shapiro et al. showed that pulses shorter than 2 ms evoked inward currents shorter in duration and higher in amplitude than 10 ms pulses¹⁰. Following the same trend, the stimulation threshold for rat brain slice cultures decreased with pulse width using photoabsorber-induced neurothermal stimulation²². Overall, stimulation appears to be more effective with shorter pulses, which potentially contain a mechanical component as these pulses are closer to stress confinement.



Figure 2.1 Stimulation thresholds across different laser parameters. (a) Pulse width does not significantly change the stimulation threshold of a diode laser at 2 ms and 350 μ s (b) A Ho:YAG laser has a lower stimulation threshold than a diode laser despite having the same pulse width of 350 μ s. Figure from Throckmorton *et al.*²⁰ licensed under CC BY 4.0.

A photomechanical mechanism has also been implicated in cochlear INS. Both direct neural stimulation and stimulation via an acoustic event have been discussed as possible mechanisms in the cochlea. Laser-induced pressure waves in water have been recorded from pulsed 1850 nm light, which indicated that laser-evoked acoustic events could cause stimulation in the cochlea^{23,24}. More evidence of an optoacoustic pressure wave from the laser light acting on the basilar membrane as the main mechanism of cochlear stimulation was found from *in vivo* experiments on hearing guinea pigs with pressure measurements²⁵. Additionally, in gerbil cochlea, Izzo *et al.* demonstrated that the stimulation thresholds for pulses up to 100 µs increased slightly, and the threshold was significantly higher for a 300 µs pulse²⁶, suggesting a mechanical contribution for the shorter pulses. However, there has also been data that show that an acoustic event does not dominate stimulation but rather direct radiation of neural tissue²⁷, making it unclear what the mechanism truly is.

Laser-induced stress and volumetric thermal expansion have previously been considered as the mechanism, but the conclusions from the experimental results dismissed a photomechanical contribution to the mechanism⁹. Since then, supporting evidence of a mechanical component to the mechanism has been more apparent with different stimulation thresholds at shorter pulses and a possible mechanical mechanism in cochlear stimulation. Based on these findings and the fact that shorter pulses are closer to stress confinement than longer pulses, we hypothesize that a mechanical component is involved in shorter pulses that results in more efficient stimulation. Using computational modeling, we can obtain an understanding of the underlying biophysics during an infrared pulse on an incident nerve. This thesis aims to investigate possible mechanical effects in peripheral nerve INS by comparing transient pressure waves and displacement modeling results to experimental stimulation thresholds at different pulse widths.

2.2 Methods

2.2.1 SESE Model

The Scalable Effects Simulation Environment (SESE) is a software package developed by Nanohmics (Austin, TX) in collaboration with the Airforce Research Laboratory (AFRL) at Fort Sam Houston in San Antonio, TX that simulates physical effects of electromagnetic radiation impinging on a complex inhomogeneous structure. SESE version 2.6.0 was used for all simulations. Time-dependent simulations in 3D were run with set geometries for the neuron's structure, laser parameters, and material properties as inputs. The details of SESE's implementation can be found in a publicly released technical report²⁸ and are briefly described here.

The optical component of the model is implemented using Monte Carlo, a statistical method to determine the spatial distribution of radiation in an object. SESE's radiative transport is performed using probabilistically weighted traced rays from the source which undergo reflection and refraction when interacting with boundaries. Within the material, absorption and scattering occur probabilistically according to the material's optical properties.

For the thermal model, a Gauss-Seidel red-black successive over-relaxation (RBSOR) method²⁹ is used to solve the heat equation in the 3D domain with a finite volume discretization. The RBSOR technique allows for rapid convergence, eliminates the need to store large matrices, and is easily parallelized. The bioheat equation for the temperature T [K] over time t is:

$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (\kappa \nabla T) + \omega p_b c_b (T_b - T) + Q$$

where ρ is density [kg/m³], c is specific heat [J/kg·K], κ is thermal conductivity [W/m·K], ω is the perfusion coefficient [1/s], and ρ_b , c_b , and T_b are the density [kg/m³], specific heat [J/kg·K], and temperature [K], respectively, of the perfusive medium. Q is the source term [W/m³], which is the radiative energy distribution from the optical model. Radiative, convective, evaporative, and ablative boundary conditions can be selected and applied to the object's surface.

The latest addition to SESE includes a numerical implementation of thermally mediated photoacoustic effects. In short, linear elastic equations with a thermal expansion term are solved with an elastic finite-difference time-domain solver. The elastic modulus λ [Pa], shear modulus μ [Pa], and thermal expansion coefficient α [1/K] are the material-dependent mechanical properties needed to solve for the transient pressure response. The elastic and shear moduli are Lame's parameters and can be calculated given the Young's modulus E [Pa] and Poisson ratio v:

$$\lambda = \frac{E\nu}{(1+\nu)(1-2\nu)}$$
$$\mu = \frac{E}{2(1+\nu)}$$

2.2.2 Modeling parameters

For modeling peripheral nerve INS, the parameters and geometry are based on the setup that was used by Throckmorton *et al*²⁰. The geometry (Figure 2.2) is set up as a 1.5 mm diameter rat sciatic nerve embedded in a 4 mm x 4 mm x 2 mm block of tissue surrounded by air. Since the nerve is exposed to air, a free convective boundary was selected. The tissue material properties mimic skin and should not affect the simulation significantly as the nerve absorbs all the radiative energy. A 400 μ m diameter optical fiber (NA=0.22) is placed 862 μ m above the top surface of the center of the nerve with the fiber in air as the surrounding medium. The measured spot size at the tissue surface was ~ 500 μ m (knife edge and confirmed with a Thorlabs beam profiler)²⁰, so this was used for the simulation radiant exposures.



Figure 2.2 Geometry used for INS parameter simulations

Table 2.1 lists the optical, thermal, and mechanical properties used to model the mechanical response during INS on a rat sciatic nerve and polyacrylamide gel for model validation. The properties listed are assumed to be at an ambient temperature of 20°C, except for the volumetric thermal expansion coefficient which has temperature-dependent values.

Optical properties	Material	Value	Reference
Absorption Coefficient μ _a	Nerve	22.9 cm ⁻¹ at 1470 nm 22.7 cm ⁻¹ at 2120 nm	Ezekiel Haugen's work submitted for publication
	Water/gel	24 cm ⁻¹ at 2120 nm	20,30
Scattering Coefficient µs	Nerve	205.3 cm ⁻¹ at 1470 nm 173.5 cm ⁻¹ at 2120 nm	Ezekiel Haugen's work submitted for publication

	Water/gel	0 cm ⁻¹	
	Nerve	0.9 at 1470 nm and 2120	Ezekiel Haugen's
Anisotropy g		nm	work submitted
			for publication
Index of refraction	Water/nerve/gel	1.33	
Thermal properties	Material	Value	Reference
Density p	Water/nerve	1075 kg/m ³	31
	Polyacrylamide gel	1030 kg/m ³	32
Thermal conductivity k	Water/nerve	0.49 W/m·K	31
	Gel	0.55 W/ m·K	32
Specific heat capacity c _p	Water/nerve	3613 J/kg·K	31
	Gel	3950 J/kg·K	32
Convection coefficient h	Ambient air	$10 \text{ W/m}^2 \cdot \text{K}$	33
	Gel	N/A	
Mechanical properties	Material	Value	Reference
Young's modulus E	Nerve	580,000 Pa	34
	Gel	25,000 Pa	35
Poisson ratio v	Nerve	0.37	36
	Gel	0.474	35
Volumetric thermal	Water	0.0002°K ⁻¹ at 20°C	37,38
expansion coefficient α_v		0.00025°K ⁻¹ at 25°C	
		0.0003°K ⁻¹ at 30°C	

The optical, thermal, and mechanical properties of materials, especially live tissues, are difficult to measure. The properties listed here either use properties that were measured but might be in different experimental conditions or assume that of water since both nerve and polyacrylamide gel are mostly made up of water, which is the main chromophore for INS. Rat sciatic nerve optical properties have recently been collected from *ex vivo* fresh hydrated nerve by Haugen *et al.* (submitted for publication). Thermal properties of nerve are unknown and therefore are assumed to be that of water. The Young's modulus for nerve was taken from a fresh, whole rat sciatic nerve³⁴ and the Poisson ratio from fresh adult cadaver sciatic nerve³⁶. For 10% polyacrylamide gel, the optical properties of water are assumed, and thermal properties were found in the literature. The volumetric thermal expansion coefficient of both nerve and gel is assumed to be that of water^{37,38}. The gel thermal properties are based on a 10% concentration of acrylamide and 90% water³². The convection coefficient is set as 10 W/m²·K, which is typical of free air convection³³.

2.2.3 SESE Model Validation

To confirm that the SESE model outputs are accurate, validation of the model is needed. The optical and thermal components of the model have been verified against analytical solutions, with more details in the technical report²⁸. Additionally, skin damage thresholds from SESE photothermal modeling³⁹ compared well to experimental data⁴⁰. The mechanical part has been compared to two existing models for verification, a published photoacoustic k-space propagation model⁴¹ and COMSOL's linear elastic finite-difference time-domain code. Although SESE compares favorably to both these models, it has not been compared to experimental data and is therefore completed in this study.

2.2.3.1 SESE Displacement Validation

A previous study by Wells *et al.* measured the surface displacement of a rat sciatic nerve using differential phase optical coherence tomography (DP-OCT)⁹. To validate the displacement from the modeling results, the modeling inputs were set to match the Wells experimental setup. The geometry was configured for INS modeling on rat sciatic nerve using the geometry

mentioned above, with a Ho:YAG laser at a wavelength of 2120nm coupled to a 600 μ m diameter multimode fiber (NA = 0.39) placed 0.75mm from the surface of the nerve. The z-displacements were recorded from the model at radiant exposures 0.2, 0.4, 0.6, and 0.8 J/cm².

2.2.3.2 SESE Pressure Validation

For validating pressure from the SESE model, polyacrylamide gel was chosen as this gel is mostly made up of water but also has mechanical rigidity and similar mechanical properties to tissue. A 10% polyacrylamide gel was made with 0.1% bisacrylamide as the crosslinker and poured into a 5 cm x 5 cm 3D printed mold, which was mounted and has an opening that allows the optical fiber to be inserted into the gel from the bottom of the mold. A needle hydrophone (HNC-0200, ONDA, Sunnyvale, CA) was positioned 1mm away from the optical fiber using a micromanipulator. The laser and oscilloscope were triggered with a digital delay/pulse generator (DG535 Stanford Research, Sunnyvale, CA). Pressure waveforms were collected with PicoScope 7 software. A 350 μ s pulse from the Ho:YAG coupled with a 600 μ m fiber outputting 31mJ was tested. This pulse energy was used to stay below the ablation threshold. The modeling parameters were set up to closely match the experimental parameters used for validation. The parameters listed in the next section were used for investigating INS mechanical effects and are different from the validation parameters in this section.

2.2.4 Infrared neural stimulation parameters

Four different pulse duration and laser combinations (Table 2.2) were assessed for modeled pressures and displacements. Three of these laser parameters are taken from Throckmorton *et al.*: a free-running 350µs pulse from a 2120nm Ho:YAG laser, a 350µs pulse from a 1470nm diode laser, and a 2ms pulse from a 1470nm diode laser²⁰. To investigate the effect of just the spike portion of the Ho:YAG pulse, this modeling study includes the addition of a short pulse Q-switched 2120nm Ho:YAG laser with a pulse duration of 100ns.

Laser	Wavelength	Nerve absorption	Pulse width	Spot size	Radiant
	(nm)	coefficient (cm ⁻¹)	(µs)	(µm)	exposures
					(J/cm ²)
Diode	1470	22.9	350		0.5 to 2
Diode	1470	22.7	2000	500	0.5 to 2
Ho·YAG	2120	22.7	0.1	500	0.5 to 2
110.1710	2120	22.1	350		0.5 to 2

 Table 2.2 INS Parameters

To be consistent with Throckmorton *et al.*, a 400 μ m optical fiber (NA=0.22) was used for all INS simulations, and a 862 μ m fiber-to-nerve distance was held constant. To assess the mechanical effects, specifically displacement and pressure, simulations were run for four different radiant exposures spaced evenly between 0.5 and 2 J/cm² for each laser parameter combination. To capture the pulse and effects after the pulse, simulations were run for a total of 1 ms for the 100 ns and 350 μ s pulses and 4 ms for the 2 ms pulses.

2.2.5 Data analysis

The outputs from the model included temperature, displacement in x, y, and z directions, and the stress tensor at all positions in time and were visualized in ParaView. A single location at the surface of the nerve in the center was selected for observing the results where the laser pulse energy gets absorbed. Pressure is the negative of hydrostatic stress. From the stress tensor, we can calculate the pressure P as the average of the normal stresses:

$$P = -\frac{1}{3} \left(\sigma_{xx} + \sigma_{yy} + \sigma_{zz} \right)$$

2.3 Results

2.3.1 SESE displacement validation

Modeled z-displacements at the top surface of the nerve across radiant exposures 0.2-0.8 J/cm^2 (Figure 2.3(b)) are very similar to (within 5% of) DP-OCT displacements recorded by Wells *et al.* (Figure 2.3(a)). At 0.4 J/cm^2 , the peak z-displacement is 295 nm, which is nearly the same displacement of 300 nm that Wells measured. The displacement over time at 0.4 J/cm^2 was only modeled up to 25 ms due to the heavy computation time but showed the same trend as the optical path length change of a rapid displacement change of ~300 nm and slow relaxation back to baseline.



Figure 2.3 SESE model shows good agreement with experimental surface displacement values. (a) DP-OCT experimental results reproduced from Wells *et al.*⁹ with permission from Elsevier. (Left) Surface displacement measurements over range of radiant exposures (Right) Optical path length change recording over time at 0.4 J/cm² corresponding to 300nm displacement (b) SESE model displacement results (Left) modeling displacements at 0.2 J/cm², 0.4 J/cm², 0.6 J/cm², and 0.8 J/cm². (Right) Modeled displacement over time at 0.4 J/cm² corresponding to 295nm displacement.

2.3.2 SESE pressure validation

The experimental setup for pressure validation is shown in Figure 2.4(a). For the pressure validation laser parameters (350 μ s Ho:YAG pulse), both the experimentally measured and modeled pressures (Figure 4(b)) are very small (<100 Pa) and have positive (compressive) and negative (tensile) components. The experimental pressure is notably larger in magnitude than the modeled pressure, but both are on the same order of magnitude and oscillate similarly.



Figure 2.4 Pressure validation of SESE model. (a) Experimental setup for pressure validation of SESE model. The hydrophone was placed into 10% polyacrylamide gel 1 mm away from the 600 μ m optical fiber. (b) Modeled vs. experimental pressure from free-running 350 μ s Ho:YAG with 31 mJ output.

2.3.3 Temperature profiles

The modeled temperature rises across the different pulse durations and profiles are similar, with $\Delta T = 6.5$ °C for both Ho:YAG pulses (100 ns and 350 µs), 6.7 °C for the diode 350 µs pulse, and 6.6 °C for the diode 2 ms pulse (Figure 2.5(a-h)). Looking at the surface temperature over time (Figure 2.5(i)), each parameter shows the same trend: the temperature increases to the max temperature during the pulse, then diffuses slowly as time continues. As expected, the shorter pulses have a faster time to max temperature (dT/dt) since the pulse energy is deposited more quickly.



Figure 2.5 Temperature profiles across laser pulse profiles are similar. Area under curve-normalized temporal pulse profiles for (a) a 100 ns Ho:YAG pulse (b) free-running 350 μ s Ho:YAG pulse (c) 350 μ s diode pulse (d) 2 ms diode pulse. Spatial temperature profiles (1 J/cm²) at the end of the pulse for (e) 100 ns Ho:YAG pulse, (f) free-running 350 μ s Ho:YAG pulse, (g) 350 μ s diode pulse, (h) 2 ms diode pulse. (i) Surface temperature over time compared across different parameters at 1 J/cm².

2.3.4 Displacement and pressure compared to stimulation efficiency

The displacement and pressure were modeled for a range of radiant exposures, showing a linear trend with radiant exposure. The maximum z-displacements across radiant exposures (Figure 2.6(a)) show that the100 ns Ho:YAG has slightly larger displacements than the other pulses, especially at higher radiant exposures. The other pulses have nearly identical max displacements. Similarly, the maximum pressure, defined as the maximum positive or compressive pressure, is identical across the pulses except for the 100 ns Ho:YAG, which has much higher pressures (Figure 2.6(b)). The minimum pressure, defined as the maximum negative or tensile pressure, is much larger in magnitude for the 100 ns pulse than the other pulses. Additionally, the 350 µs Ho:YAG pulse shows slightly larger negative pressure than the diode pulses (Figure 2.5(c)).



Figure 2.6 Maximum displacement and pressure are higher for shorter pulses across radiant exposures. (a) Maximum surface z-displacement (b) Maximum pressure, defined as the maximum positive or compressive pressure (c) Minimum pressure, defined as the maximum negative or tensile pressure, at the surface across a 100 ns Ho:YAG pulse, 350 μ s diode pulse, and 2 ms diode pulse.

To draw a fair comparison, the displacement and pressure over time at the same radiant energy (1 J/cm^2) were examined. The x, y, and z-displacements over time are plotted for each pulse in Figure 2.7(a-d). The z-displacement is much higher than the x and y displacement. Each of the pulses reach similar max displacements, but the 100 ns Ho:YAG pulse has a higher z-

displacement and significant fluctuations. Minor fluctuations are also shown in the 350 μ s pulses, more so in the Ho:YAG pulse than the diode. The pressure across the different pulses varied based on the pulse shape and duration (Figure 2.7(e)). A pressure spike with a much larger pressure (~1300 Pa) than any of the other pulses is evident for the 100ns Ho:YAG. There is also a spike for the 350 μ s Ho:YAG, but this is much smaller in magnitude (~100 Pa). For the overall duration of the pulse, the 350 μ s Ho:YAG and 350 μ s diode pulses have a similar rise in pressure to about 100 Pa. The 2ms pulse shows a very gradual linear pressure increase for the duration of the pulse. The stimulation thresholds previously determined by Throckmorton *et al.* are shown for comparison to the modeled mechanical effects (Figure 2.7(f)).



Figure 2.7 Displacement and pressure (1 J/cm²) compared to stimulation threshold. (a-d) x, y, and z-displacement over time for 100 ns Ho:YAG pulse, 350 μ s Ho:YAG pulse, 350 μ s diode pulse, and a 2 ms diode pulse. (e) Pressure over time at 1 J/cm² (f) Stimulation thresholds for 350 μ s Ho:YAG pulse, 350 μ s diode pulse, and a 2 ms diode pulse. Adapted from Throckmorton *et al.*²⁰

2.4 Discussion

Modeling the biophysical effects of INS computationally provides a deeper look into what exactly occurs during stimulation with a laser pulse. Thermal modeling of INS has been performed previously^{42,43}, as well as the characterization of a thermal gradient as part of the INS mechanism⁹. Recent evidence has pointed towards a mechanical component, but this has yet to be investigated for peripheral nerve INS. SESE provides a combined optical-thermal-mechanical model that is used here to determine the underlying mechanical effects of various laser parameters. To be able to accurately evaluate the results from the SESE model, it must first be validated. Surface displacement values for a rat sciatic nerve were compared to Wells et al. experimental data from 2007 and showed good agreement across multiple radiant exposures (Figure 2.3). Additionally, pressure measurements in polyacrylamide gel confirm that the pressures produced from INS energies for typical pulse durations (hundreds of µs or longer) are very small (<100 Pa) (Figure 2.4), especially compared to pressures involved in photoacoustic imaging (on the order of 10 kPa) or ultrasound (on the order of 1 MPa)⁴⁴. While the experimental and modeling pressures do not match exactly, they both are such small pressures within the same order of magnitude. These pressures are difficult to experimentally measure and are minimal, which the modeling confirms. Future work with a short pulse Ho:YAG with low energy, which would induce higher pressures that are easier to measure, should be completed to further validate the model. With SESE's previous temperature validation^{39,40}, these validation results of displacement and pressure show that SESE is a promising tool that can be utilized for multiphysics modeling of different processes.

Since the discovery of INS, the mechanism has been hypothesized to be primarily a photothermal effect driven by water absorption from a thermal gradient. The spatial and temporal temperature profiles were modeled and examined for the different pulse parameters (Figure 2.5). Approximately the same temperature rise ($\Delta T = 6.6 \pm 0.1^{\circ}$ C) was observed for each of the pulses, but the rise time to the maximum temperature corresponded with pulse width. The diode pulses have slightly higher temperature rises than that of the Ho:YAG pulses, which can be explained by the higher absorption coefficient at 1470 nm ($\mu_a = 22.9 \text{ cm}^{-1}$) compared to the absorption coefficient at 2120 nm ($\mu_a = 22.7 \text{ cm}^{-1}$). Due to the longer pulse duration, which likely allowed some diffusion, the diode 2ms pulse has a slightly lower ΔT than the 350 µs pulse.

Following the rise to the maximum temperature at the end of the laser pulse, the temperature decays back to the baseline temperature over a thermal relaxation time τ_{th} which is defined as the time required for the peak temperature to decay to 1/e (37%) of the total temperature rise⁴⁵. The thermal relaxation time is independent of pulse duration, and the calculated value (from τ_{th} = $\delta/4\alpha$) is 215 ms while it was experimentally found to be 90 ms for rat peripheral nerve⁹. Although the 350 µs Ho: YAG and 350 µs diode pulses have nearly identical thermal gradients, the Ho:YAG has a lower stimulation threshold, which is hypothesized to be from the microsecond energy spike at the beginning of the pulse²⁰. While the mechanism might be primarily photothermal, this difference in thresholds suggest other mechanisms might also be involved. Thompson et al. presented thermal modeling results that were compared to Izzo et al. and Richter et al. cochlea data^{26,46,47} and suggested two regimes for stimulation: for pulses <100 μ s, a minimum temperature is needed for stimulation and for pulses $\geq 100 \ \mu$ s, a thermal gradient is needed to achieve stimulation⁴². With the shorter pulses only needing a minimum temperature, some other contribution must be involved to achieve the stimulation the other pulses obtain with a thermal gradient. Together, these findings affirm the idea that multiple biophysical processes are involved in the INS mechanism.

Volumetric expansion occurs when a material expands due to heating, whereas thermoelastic expansion requires stress confinement (typically from a short pulse) and generates pressure waves. As shown in Figure 2.5, the different pulse parameters reach the same temperature over each respective pulse duration. Thus, the nerve would be expected to expand the same amount in each case. The modeled z-displacements represent the expansion of the nerve in the direction of the laser. Looking at the maximum displacement values (Figure 2.6(a)), all pulses had around the same surface displacement at each radiant exposure (~170 nm peak), but the 100ns pulse had a slightly higher displacement (~200 nm peak). When comparing the displacement over time at the same energy across the pulses (Figure 2.7 (a-d)), there are noticeably large fluctuations for the 100 ns pulse, smaller fluctuations for the 350 µs pulses, and no visible fluctuations for the 2ms pulse. These fluctuations can be attributed to vibrations occurring at the surface membrane, which likely causes membrane deformations. Plaskin *et al.* showed that a thermally induced deformation in the membrane induces a capacitance increase that leads to depolarization¹¹. The displacement modeling results support the idea that volumetric expansion causes membrane deformations, which then induces a capacitance change. However,

this is likely not entirely a thermal effect. While the temperature gradient is quicker for shorter pulses which could lead to a larger capacitance increase, there seem to be underlying pressures from thermoelastic expansion that might also contribute, shown by the membrane fluctuations of the shorter pulses (100ns Ho:YAG and 350µs Ho:YAG with spike).

The modeling results show that pulse profiles impact transient pressures. Similar to how temperature-sensitive channels might be involved in the INS mechanism, we hypothesize that mechanosensitive channels could also play a role. Various mechanosensitive channels have been investigated for ultrasound stimulation. Yoo *et al.* found that in cortical neurons, mechanosensitive channels TRPP1/2, TRPC1, and Piezo1 respond to mechanical interactions, which then opens TRPM4 channels and causes depolarization⁴⁸. TRAAK K⁺ channels in *Xenopus* oocytes were found to be sensitive to pressure (-15 mmHg = -2000 Pa), which caused channel opening due to membrane tension ⁴⁹. Piezo2 was observed to be essential for mechanical firing in a subset of mouse sensory neurons⁵⁰. Kubanek *et al.* showed that focused ultrasound modulates K⁺ and Na⁺ currents through K2P and Na_v1.5 channels⁵¹. The modeled pressures for INS parameters (100-1000 Pa at 1 J/cm²) are very small, especially compared to those used for ultrasound neurostimulation (in the MPa range)⁵². However, a large pressure might not be needed to cause stimulation. In fact, Piezo2 was activated by a low threshold positive pressure (5 mmHg = 666 Pa)⁵³. The small pressures found by these modeling results could be enough to activate mechanosensitive channels and help initiate stimulation.

Higher pressures resulted from shorter pulses (100 ns Ho:YAG) or pulses with a short energy spike (350 μ s Ho:YAG). Our results also show that higher pressures correlate with lower stimulation thresholds, suggesting a mechanical effect leads to more efficient stimulation. Throckmorton *et al.* previously showed that a 350 μ s Ho:YAG laser had a lower stimulation threshold than a 350 μ s diode laser. These pulses have nearly identical temperature profiles at 1 J/cm² (Figure 2.5). Looking at the displacement and pressure, we can see the differences that the 1 μ s spike of the 350 μ s Ho:YAG causes, which includes a small pressure spike at the beginning and slightly more displacement fluctuations. The 350 μ s and 2 ms diode pulses have similar stimulation thresholds but also have the same max pressure and displacement. The 100 ns pulse had a much higher pressure at 1 J/cm² in addition to a larger surface displacement with many fluctuations. We hypothesize that these more prevalent mechanical effects would lead to an even

lower stimulation threshold than that of the 350 µs Ho:YAG pulse. Further work should be done to determine the stimulation threshold of the short pulse Ho:YAG to confirm that mechanical effects are important in INS efficiency.

2.5 Conclusion

Computational modeling can be a useful tool for estimating the amplitude of photomechanical effects such as pressure transients during INS. There are higher magnitude mechanical effects, namely pressure and displacement changes, during shorter pulses or pulses with an initial energy spike. Higher magnitude pressure transients and larger displacement fluctuations also appear to correlate to lower stimulation thresholds. The data from this modeling study supports that shorter pulses result in more significant mechanical effects, specifically pressure and displacement changes, and thus supports the hypothesis that there is indeed a mechanical component to the INS mechanism. This insight will allow for finer tuning of the laser parameters needed for INS to move towards clinical applications.

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