

ON-CHIP CHARACTERIZATION OF SINGLE-EVENT
CHARGE-COLLECTION

By

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CHAPTER I

INTRODUCTION

With a decrease in device dimensions and operating voltages of integrated circuits (ICs), their sensitivity to radiation increased dramatically [1]. One of the major reliability challenges in deep sub-micron technologies is single-event effects (SEEs) [2]. When highly energetic particles (e.g., protons, neutrons, alpha particles or other heavy-ions) strike sensitive regions of microelectronic circuit, the particle strike may cause a transient disruption of circuit operation (single-event transient) or a change of logic state of the circuit (single-event upset). These effects are referred to as soft errors because the device/circuit itself is not permanently damaged by radiation and the errors can be corrected by new data.

When a radiation particle strikes a semiconductor material, charge is generated either by direct ionization of the incident particle itself, or due to the ionization by secondary particles caused due to nuclear reactions between hit device and the incident particle. Following charge generation, the high electric field present in the reverse biased junction depletion region of the transistor collects charge through drift and diffusion processes leading to a transient current at the terminals of the hit transistor.

Using TCAD models, it is possible to examine the charge collection processes after particle strikes and gain an insight into the mechanisms that occur on a pico-second time scale. In older technologies, the charge cloud created due to an ion strike affected only a single transistor due to large separation between them. Thus, the charge collection process in most

cases was limited to drift and diffusion processes for a single p-n junction [3]. However for advanced technology nodes, charge collection process is complex due to several factors, such as increased carrier concentrations [4], ambipolar carrier mobilities [4], multiple transistors in the charge track collecting charge [5-6], and parasitic bipolar amplification of single event related currents [7-12]. Further, the collected charge is also affected by the circuit and layout parameters at the hit node; such as restoring device characteristics [6] and the presence of multiple devices within a certain distance [44]. TCAD simulations are limited to just a few devices contained in a small region due to computational complexities and these effects may or may not be accurately modeled using TCAD. Hence, experimental verification of charge collection is desirable to develop accurate predictive TCAD models for future technologies.

This thesis presents an autonomous charge collection measurement circuit technique to experimentally characterize charge collection, or charge sharing processes, and is organized as follows. Chapter II provides a brief overview of the various mechanisms of single events and also some of the existing measurement circuits developed to experimentally characterize single event charge collection as part of motivation behind this work. Chapter III presents an on-chip autonomous charge collection measurement technique to experimentally verify charge collection processes for advanced technologies. Simulation results of the circuit designed in a 40 nm CMOS process are discussed in Chapter IV. As a conclusion, a summary is provided in Chapter V.

CHAPTER II

SINGLE EVENT EFFECTS – OVERVIEW

Types of radiation particles

This section briefly outlines the space radiation environment in terms of charged particles and its sources that are capable of affecting integrated circuits (ICs). High energy radiation particles could be categorized as originating from - (1) Trapped radiation (2) Solar flares and (3) Cosmic rays

Trapped radiation environment

This includes two major radiation belts that originate from different sources – (1) inner belt that is formed from the cosmic radiation (also referred to as ‘proton’ belt or ‘Van Allen’ belt) (2) outer radiation belt trapped in the magnetosphere is composed of plasma or ionized gas continually emitted by the sun. Van Allen belts are populated by protons of energies between 10-100 MeV range and hence are referred to as proton belts [13]. As for the outer radiation belt, it is the sun’s corona that emits the solar wind. When the solar wind activity is high, it diverts the galactic cosmic rays (another source for single-events) away from the earth’s magnetosphere and when the activity is weak, it allows these cosmic rays into the earth’s atmosphere.

Solar Flares

Solar flares are explosions on the sun's surface. They are the major source of protons and electrons. Coronal mass ejections, a type of solar flare occurs when huge bubbles of gas are ejected from the sun's surface. They are also found to be rich sources of protons.

Cosmic Rays

Cosmic rays could be classified as – (1) galactic cosmic rays (2) solar cosmic rays and (3) terrestrial cosmic rays. Galactic cosmic rays are composed of high-energy charged particles from supernova explosions. These rays are abundant sources of protons although a small percentage (~ 1%) of the rays comprise heavy-ions [14]. Solar cosmic rays similar to solar flares originate from the sun's surface and are sources of protons, electrons, gamma rays and X-rays. Cosmic rays penetrate the earth's atmosphere and interact with the earth's atmospheric atoms giving rise to secondary reactions. These consisting mostly of protons, neutrons, electrons, and photons are primary components terrestrial cosmic rays [15].

Basic Single Event Mechanisms

In the previous section, the sources of radiation particles were identified. This section focuses on the fundamental mechanisms resulting in single event effects (SEEs). The basic process of interaction of an ionizing particle with Silicon could be divided into three stages - (1) charge generation, (2) charge collection, and (3) circuit response [16-18]. Charge generation depends on the mass and energy of the incident ion and the properties of the materials through which it passes. Charge collection depends on many factors, such as applied bias, doping concentrations of the semiconductor, and differs from one transistor to another in the same circuit. Lastly, the circuit response depends on the circuit topology and determines if the single event (SE) leads to a

single-event transient (SET) (a voltage transient that may get latched) or single-event upset (SEU) (a bit flip in a latch). These processes are discussed below in greater detail.

Charge Generation

When an ionizing particle interacts with the semiconductor material, it releases charge in the semiconductor material either by - (1) direct ionization by the incident particle itself or (2) indirect ionization by the secondary particles created by nuclear reactions between the incident particle and the struck transistor. These processes are briefly discussed as follows -

Direct Ionization

When an ionizing particle passes through the semiconductor material it releases electron-hole pairs along its path as it loses energy. When the particle loses all of its energy, it comes to rest having travelled a total length referred to as *particle range*. To describe the energy loss per unit path length of the particle, a term called *linear energy transfer* (LET) is used. Generally to understand the particle interaction with Silicon, Bragg curves describing LET of particles against the depths travelled are studied. Such curves are computed using computer codes (TRIM, SRIM family of codes [19]). For a detailed discussion on Bragg curve, readers are referred to [20]. Typically for heavy-ions, the primary charge deposition mechanism is direct ionization.

Indirect Ionization

Protons and neutrons produce significant upsets due to indirect mechanisms [21-23]. When a high-energy proton or neutron enters the semiconductor material, any one of these several interactions may occur – (1) an inelastic collision with the Si target nucleus that may further result in the emission of alpha or gamma particles and recoil of the daughter nucleus (i.e., Si

transient at the terminals of the transistor. Even in the case of strikes near the depletion region of a transistor, carriers may *diffuse* into the vicinity of the depletion region field and collect charge resulting in transient currents. Figure 1 illustrates an ion-strike on a reverse-biased p-n junction. Additionally, ‘funnel effect’ and its influence on the transient charge collection characteristics has been investigated by several researchers at IBM [25, 26-27]. While computing the response of reverse-biased p-n junctions to alpha-particle strikes, researchers found the existence of a transient disturbance in the junction electrostatic potential and termed this the ‘field funnel’. This funneling effect may increase the charge collection at the hit transistor by extending the junction electric field away from the junction and further deep into the substrate. For comprehensive discussions on funneling, readers are referred to [28-31].

Charge Collection Enhancements

For advanced technologies, charge collection process is complex due to several factors such as multiple devices along the charge track collecting charge [5-6], increased carrier concentrations [4], ambipolar carrier mobilities [4], and parasitic bipolar amplification [7-12] of single event related transient currents. Some of these charge collection enhancement effects are discussed below briefly.

Parasitic Bipolar Amplification Effect

An effect first observed in Silicon-on-Insulator (SOI) metal oxide semiconductor (MOS) devices, that could become important for bulk MOS devices, is the parasitic bipolar enhancement effect. One of the important aspects in modeling SOI devices to an ion-strike is the isolated body region. Whether this region is electrically floating, or connected to the source region by a low-resistance strap (body-tie), any charge deposited in this region due to a single event must

recombine or exit the region through one of these three methods – (1) across the body-source junction (2) across the body-drain junction (3) out the body-source tie. Because both the junctions are reverse biased, most of the ionic charge exits the region via body-source tie. From the Figure 2, this can lead to the potential gradient from the hit location to the body tie. If the potential near the hit is large enough to cause minority carrier injection across the body source junction, then parasitic bipolar action is created between source and the drain. The current created by the ion-strike is the base current for this parasitic bipolar transistor and this base current can be amplified to create a large collector current at the sensitive node. Thus, the SE current is amplified by the gain of the parasitic bipolar transistor [32].

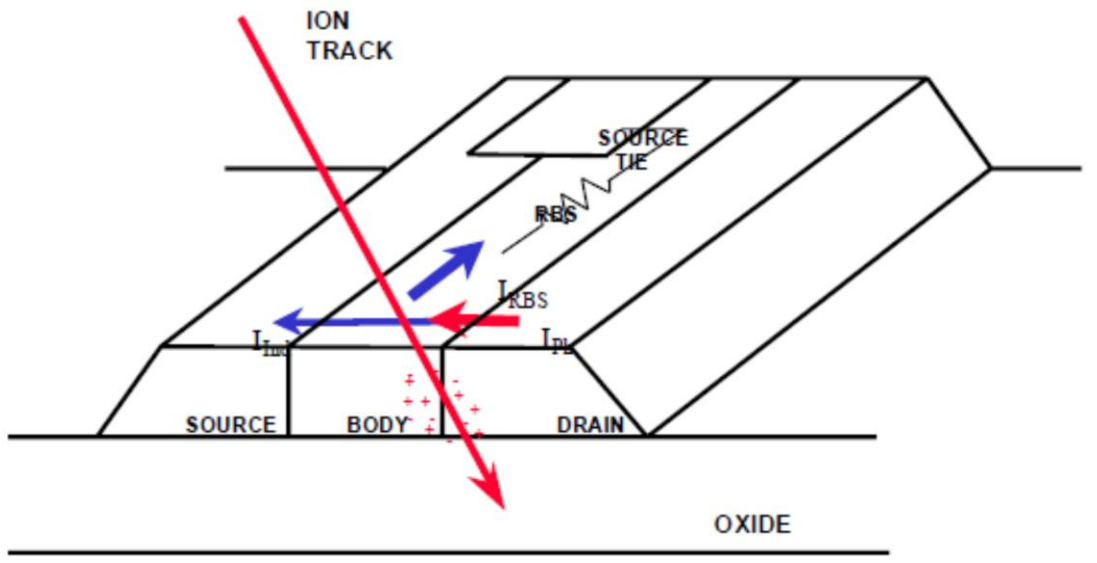


Figure 2: Relevant currents induced in a SOI device after an ion-strike^[32]

Multiple node charge generation

For deep sub-micron technologies (<250 nm), the effect of a single ion-track can be observed on multiple circuit nodes through a variety of effects as described in the earlier sections. The most obvious method that affects the multiple nodes is through diffusion. For multiple transistors in a common well, the collapse of the well potential by a single ion-strike can affect some or all of the transistors. Immediately after an ion-strike, carriers are collected by drift process due to the electric field present in the reverse biased p-n junctions. This is followed by the diffusion of the carriers from the substrate. For older technologies, the distance between the hit transistor and secondary transistor was large enough that most of the diffusion charge was also collected by the hit node. However for advanced technologies, the close proximity of the devices results in diffusion of charge to nodes other than the hit node. With a very small amount of charge required to represent a logic HIGH state at the node, the charge collected due to diffusion on an adjacent node becomes significant. Multi-node charge generation was shown by Olson *et al.*, [33] in an experiment to determine the cause of single-event upsets at energies lower than expected. Readers are referred to [33] for further details of interest on multi-node charge collection related mechanisms.

Circuit Response

The circuit response due to irradiation can either be (1) destructive effect (i.e., hard error) or (2) temporary effect (i.e., soft error). This section discusses some common destructive and temporary failure modes

Permanent Errors

Permanent errors imply irreversible damage to the functionality of the circuit, typically physical damage to the device. There are three main types of destructive SEEs – (1) single event burnout (SEB), (2) single event gate rupture (SEGR), and (3) single event latchup (SEL)

Single-event burnout (SEB) causes permanent damage to power MOSFETS and bipolar transistors [34-38]. Depending on the currents generated by the ion-strike it turns on the parasitic or active bipolar device, and triggers a regenerative feedback. If the high current is not limited, a permanent short occurs between the source and the drain and the device is destroyed [38].

Single-event gate rupture (SEGR) occurs when a charged particle passes through the gate oxide. This effect was first observed for metal nitride oxide semiconductor (MNOS) used for memory applications [39]. Later, it was also observed in MOS transistors and power MOSFETs [40]. When an ion passes through the gate oxide, a conducting plasma path is formed between the gate dielectric and Si substrate. Thus charge flows along the plasma path depositing energy in the gate oxide. If this energy is high enough, it may cause the local dielectric to melt, and evaporate the overlying conductive materials. Typically, this failure mechanism not only depends on the oxide electric field but also on the angle of the ion-strike [41].

Single-event latchup (SEL) is commonly observed in CMOS process due to the presence of n-p-n-p junction in the process. The parasitic latchup structure inherent in the CMOS process can be observed in the Figure 3 [42]. An SEL is initiated when an ion-strike causes a current flow within the well/substrate junction thereby causing a voltage drop within the well. This voltage drop leads to the forward biasing of the vertical device leading to an increased current in the

substrate. The increase in the substrate current causes a voltage drop in the substrate turning on the lateral device.

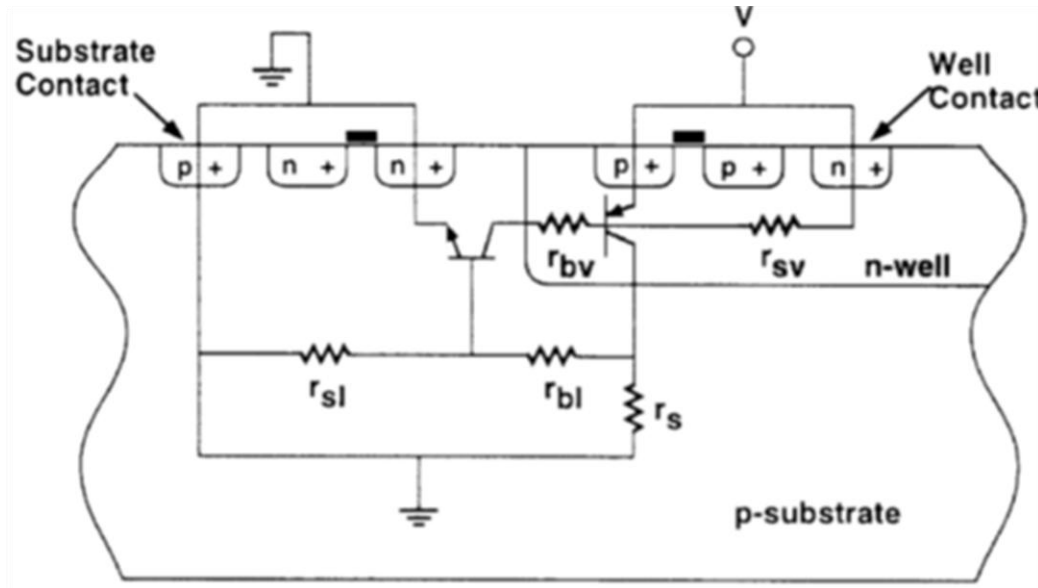


Figure 3: Illustration of parasitic latch-up structure inherent to bulk CMOS technologies ^[42]

The resulting effect is an increased current flow at the base of the vertical device initiating the positive feedback loop. Once the latchup is triggered, the sustained high current can destroy the device due to thermal failure or failure of metallization.

Temporary errors

Temporary errors can occur either as a single event transient (SET) or as a single event upset (SEU) as a result of ion-strike. An SET is a voltage glitch in the normal circuit operation due to a single event and these can occur in digital circuits as digital single event transients (DSETs) or in analog circuits as analog single event transients (ASET's). An SEU is a bit flip or change of state induced due to a single event. This change of state or upset can become an error if the signal is latched or misinterpreted as valid data by other circuitry. Multiple bit upset is another kind of

temporary error wherein multiple circuits are affected by a single event spreading to multiple nodes spaced close together.

Need For Characterization

Previous research suggests that charge-collection measurement techniques such as time-resolved ion beam induced charge collection (TRIBICC) [43] have been effective in measuring charge collection on individual devices. However, such techniques can be expensive and require large transistors for viable current measurements. For deep sub-micron technologies, the charge collected on a hit node is affected by circuit and layout parameters, such as the presence of multiple devices within a certain distance [6] and the restoring device characteristics [44]. Hence charge collection measurements must be made on transistors of relevant sizes contained within the circuit environment. Thus, an on-chip charge collection measurement circuit is desirable as the time scale of the charge collection process is in the pico-second range. Also, the measurement circuit must be able to measure a wide range of collected charge within a short time, distinguish effects of parasitic bipolar transistors [10-11], and measure the effects of charge sharing (i.e., charge collected by multiple devices due to an ion-strike). Since the charge collection process is of the same order as the switching speeds of the transistors, the measurement circuit must operate at high speeds.

Recently, an on-chip charge collection measurement circuit technique developed by Amusan, *et al.*, [45] as shown in the Figure 4, has proven effective in measuring charge collection and charge sharing processes on individual transistors contained within the circuit environment. As direct measurement of collected charge in the pico-second time scale is difficult, this measurement circuit is based on an indirect measurement of collected charge given by

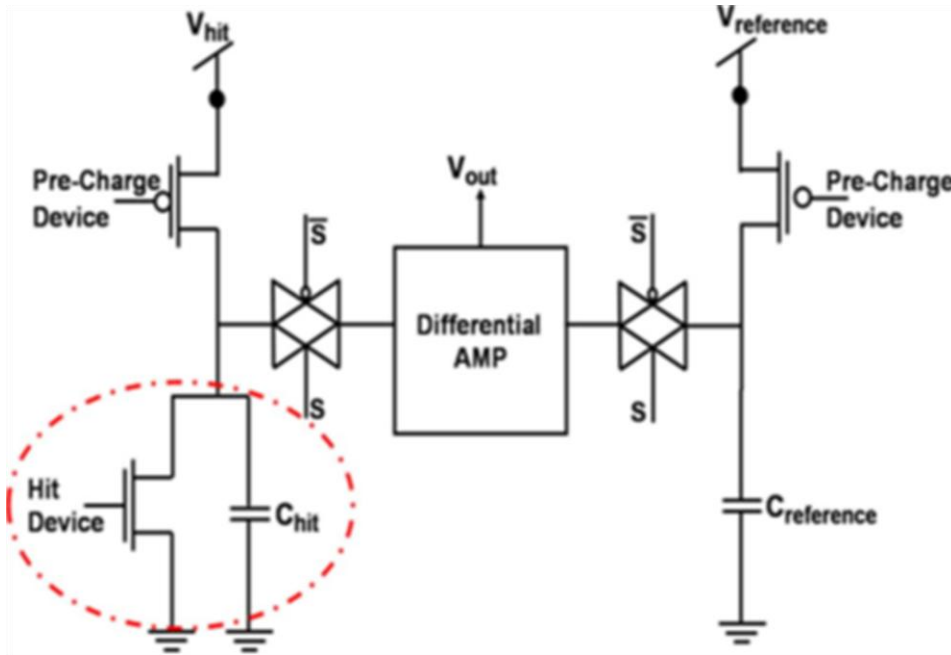


Figure 4: On-chip charge collection measurement circuit developed by Amusan *et. al.*,^[45]

$$Q = C \bullet \Delta V$$

where Q is the collected charge, C is the nodal capacitance and ΔV is the changes in the nodal voltage due to collected charge. If the nodal capacitance at the hit node is known a priori, any change in the voltage across the capacitor can be used to estimate the collected charge. The basic operation of the circuit is similar to dynamic random access memory circuits (DRAM) that are essentially capacitor voltage measurement circuits where the sense amplifier measures the voltage on the memory capacitor by comparing it against the voltage on the dummy capacitor. From the Figure 4, the capacitor associated with the hit device is charged to a known voltage value. After a laser ion-strike on the hit node, the charge collected on the hit node changes the voltage across the hit capacitor (C_{hit}). Following that, the pass gates connecting the hit and the reference nodes to the differential amplifier are closed and the hit voltage (V_{hit}) is compared against the reference voltage ($V_{reference}$). If the voltage on the hit capacitor is greater than the

voltage on the reference capacitor then the differential amplifier changes state. However, the measurement needs to be repeated with multiple values of reference voltage to exactly determine the voltage on the hit capacitor. The difference in the value of the exact hit voltage (C_{hit}) is then used to determine the exact collected charge as given by

$$Q = C_{reference} \cdot \Delta V$$

Such on-chip measurement techniques have proven effective for measuring charge collection on individual transistors. However, there are factors, such as the output voltage swing of the differential amplifier, the capacitor leakage, etc., that limit the accuracy of the measurement circuit. Also as described previously, multiple measurements may be required with different values of $V_{reference}$ to accurately determine the voltage across the hit node. Further, the measurement circuit must be a *self-triggered* design since the exact time at which the ion-strike takes place is usually unknown. Hence, there is a need to overcome these circuit limitations to make charge collection measurements. The focus of this thesis is on the design of an on-chip autonomous charge collection measurement circuit technique to overcome these limitations and hence to accurately quantify single-event charge collection processes for advanced technology nodes.

CHAPTER III

AUTONOMOUS CHARGE COLLECTION MEASUREMENT CIRCUIT

Principle of Measurement

The design of this test circuit is based on the principle that the charge collected at the drain node of a transistor is directly proportional to the voltage at a circuit node provided only capacitive loading is present as described in the previous section by -

$$Q = C \bullet \Delta V$$

Where Q is the charge collected, C is the nodal capacitance and ΔV is the changes in the nodal voltage due to collected charge. Any charge collected by a circuit node is also reflected by the changes in the voltage, assuming the capacitance is unchanged. So, if the nodal capacitance is known a priori, the change in voltage can be used to determine the charge collected at the circuit node.

Circuit Architecture

The basic architecture of this measurement circuit is similar to the architecture of a delta encoded analog-to-digital converter (ADC) or counter-ramp where the input signal and the output from digital-to-analog (DAC) converter both feed into a comparator as shown in the Figure 5. The comparator controls a counter and the circuit employs negative feedback from the comparator to

adjust the counter until the DAC's output is close enough to the input signal. Finally, the counter's output corresponds to a number proportional to the input signal value.

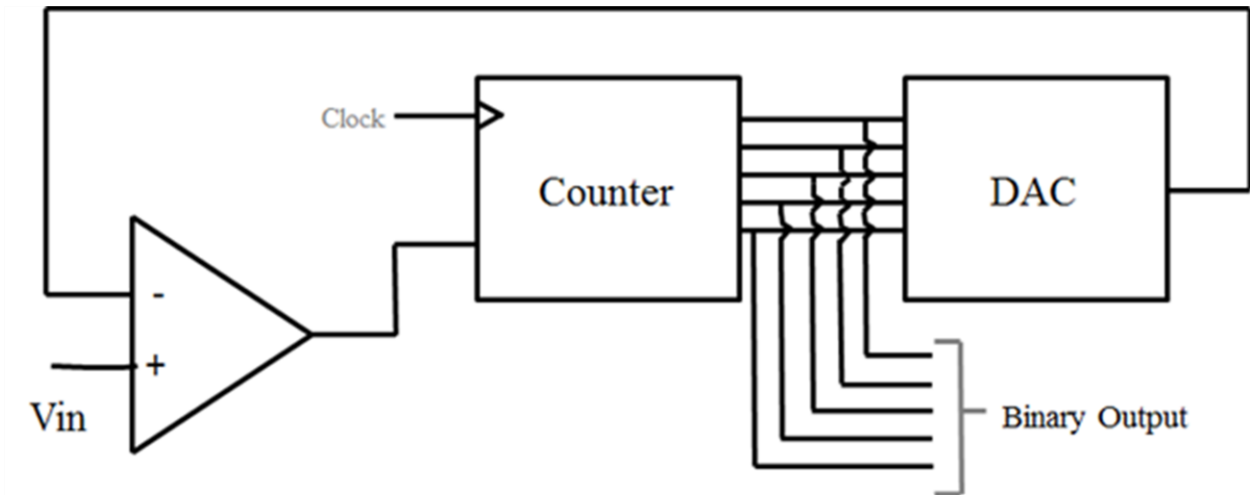


Figure 5: Delta-encoded DAC architecture

This basic delta-encoded circuit architecture modified for charge collection measurement is shown in the Figure 6.

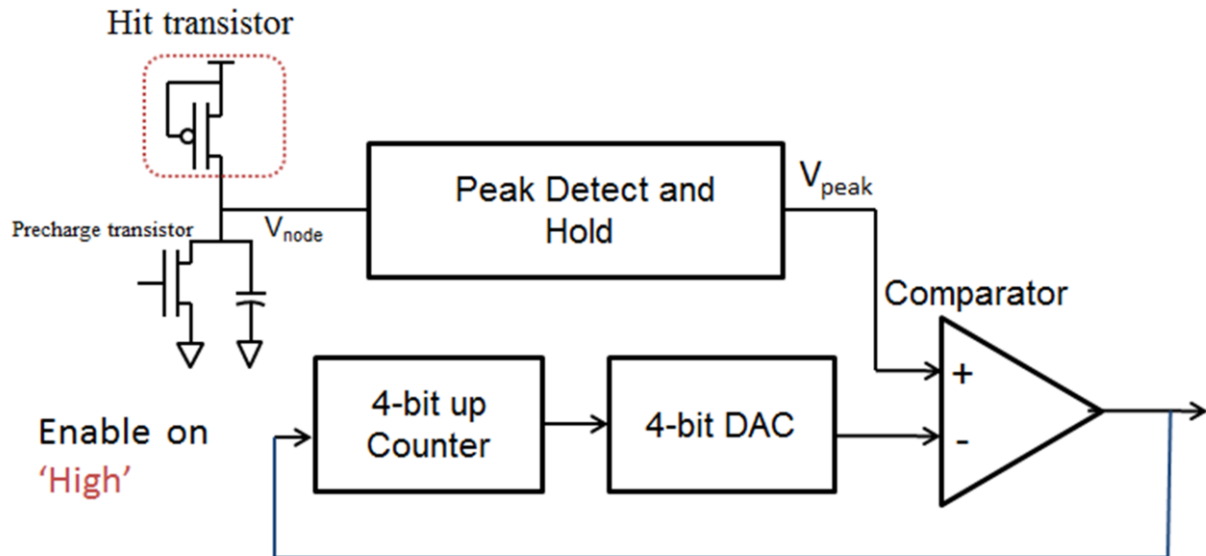


Figure 6: Autonomous charge collection measurement circuit design

From the Figure 6, it is observed that hit node is connected to the peak detect and hold (PDH) circuit. This circuit captures and holds the peak of the voltage transient generated due to an ion-strike on the hit transistor. The differential amplifier (also referred to as inverting comparator), as shown in the figure, is driven by differential signals, i.e., the output of the PDH circuit and the DAC feed its negative and positive terminals respectively. The output of the comparator through negative feedback controls the counter to increment the DAC voltage until it becomes close to the voltage across the hit node

The basic idea of operation of the measurement circuit is as follows - prior to an ion-strike on the drain of the hit transistor, its node voltage is precharged to a known value. For instance, consider an 'OFF' PMOS transistor whose node voltage is precharged to a logic '0' prior to the strike. The PDH circuit holds a '0' value corresponding to the node voltage (V_{peak}). Initially, the counter is reset and the DAC output (V_{DAC}) corresponds to its minimum offset voltage (of the order of few microvolts). Thus, the comparator is in the logic '0' state and the counter remains disabled.

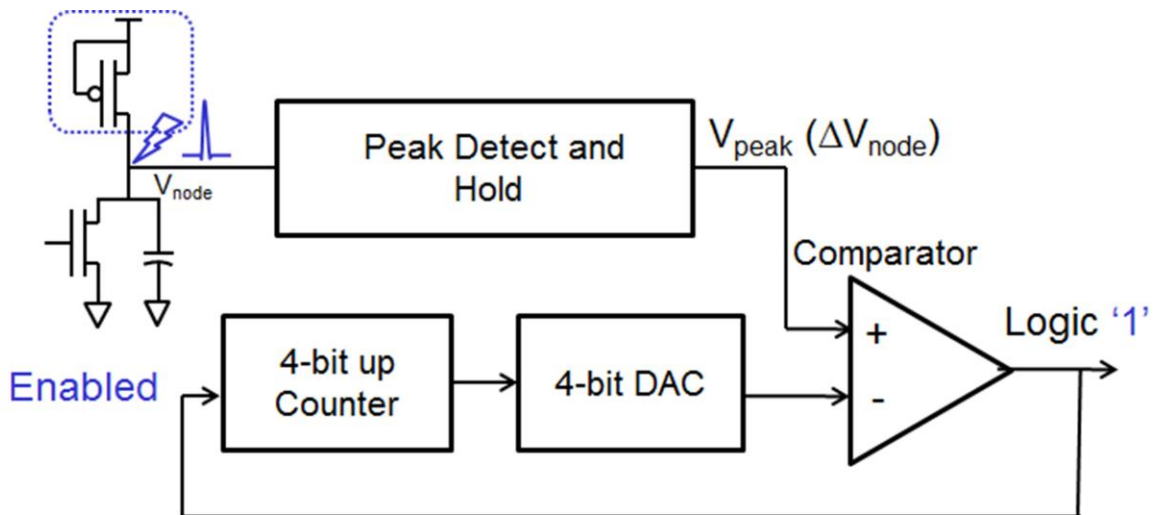


Figure 7: In response to a positive voltage transient on the target, the counter is enabled

n

the node voltage of the hit transistor is captured and held by the PDH circuit (V_{peak}). Since the

negative terminal of the comparator is now greater compared to the voltage on the positive terminal, its output changes to a logic '1' state and this in turn enables the counter that increments DAC voltage (V_{DAC}) every clock cycle until V_{DAC} exceeds V_{peak} . When V_{DAC} exceeds V_{peak} the comparator changes to logic '1' state and disables the counter. At this point, the counter value directly corresponds to the node voltage of the transistor (V_{peak}). An ion-strike on the hit transistor demonstrating the circuit operation is shown in the Figure 8.

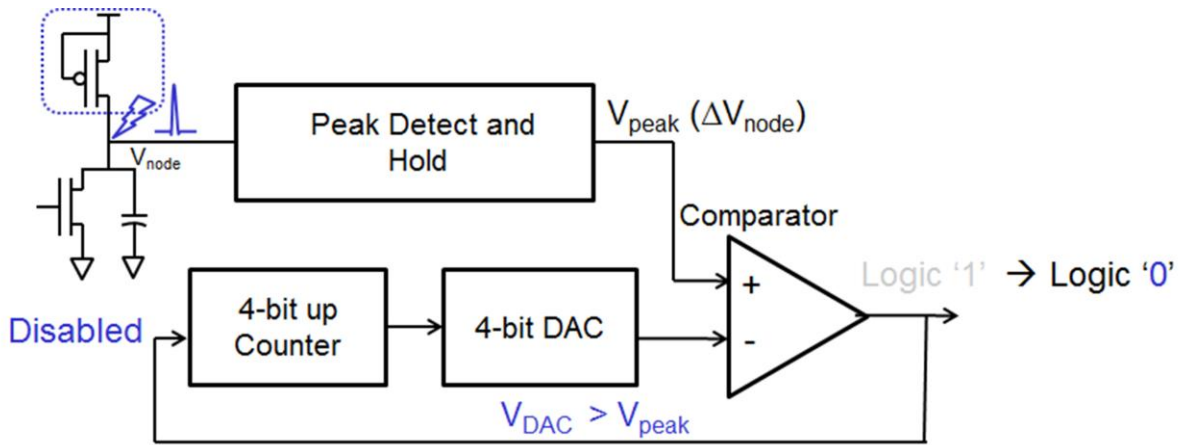


Figure 8: Counter increments V_{DAC} until it exceeds V_{peak} and the comparator disables the counter after $V_{DAC} > V_{peak}$

The design of individual circuit blocks such as PDH circuit, digital-to-analog converter (DAC), and the comparator are explained in detail in the following sections.

Peak Detect and Hold (PDH) Circuit Design

In the circuit described in the previous section, the voltage across the measurement capacitor (C_{hit}) needs to be held accurately until it is compared against V_{DAC} on every clock cycle to

exactly determine the hit voltage. Thus, there is a need for a PDH circuit to capture and hold the peak voltage across the measurement capacitor. Typically, the basic architecture of a PDH is as depicted in Figure 9 [46].

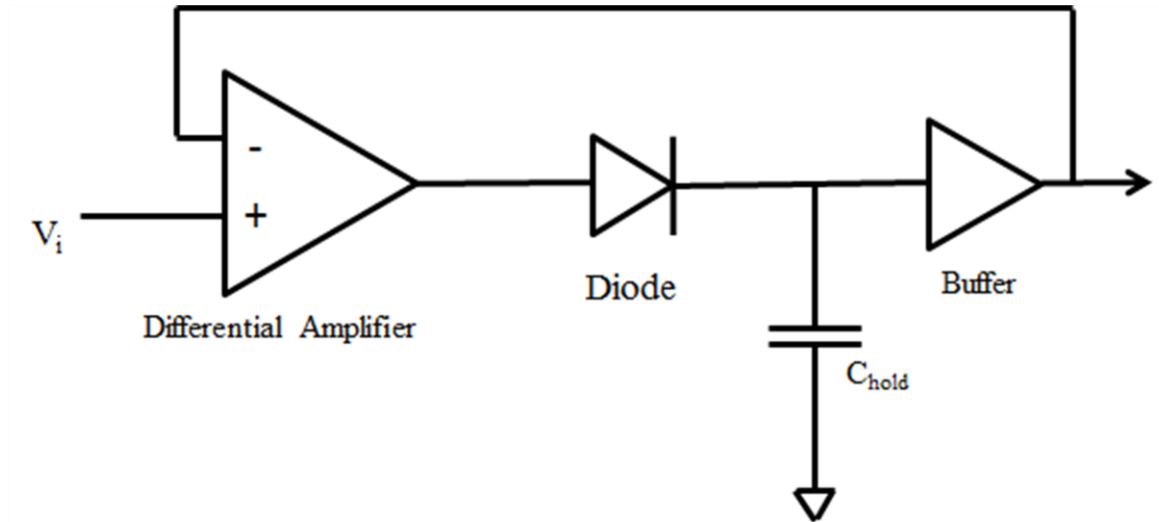


Figure 9: Basic Architecture of a peak detect and hold circuit [46]

When the input voltage is higher than the output voltage, the hold capacitor (C_s) is charged by the differential amplifier through a conducting diode. However, when the input voltage is lower than the output voltage, C_s cannot be discharged since the diode is then reverse biased. Thus, the capacitor holds the peak detected voltage. Based on this principle, several CMOS based peak detect and hold circuits were designed [47-49]. One such basic architecture modified and realized in CMOS is shown in Figure 10. The CMOS realization of the circuit is similar to the analog structure described above except that the diode is replaced by a CMOS current mirror. A current mirror replaces a diode because it generates a voltage in response to the input current and has a rectifying behavior. In other words, the output current of an pMOS current mirror as shown in the Figure 11 cannot become negative i.e., the current must flow into the mirror. This feature

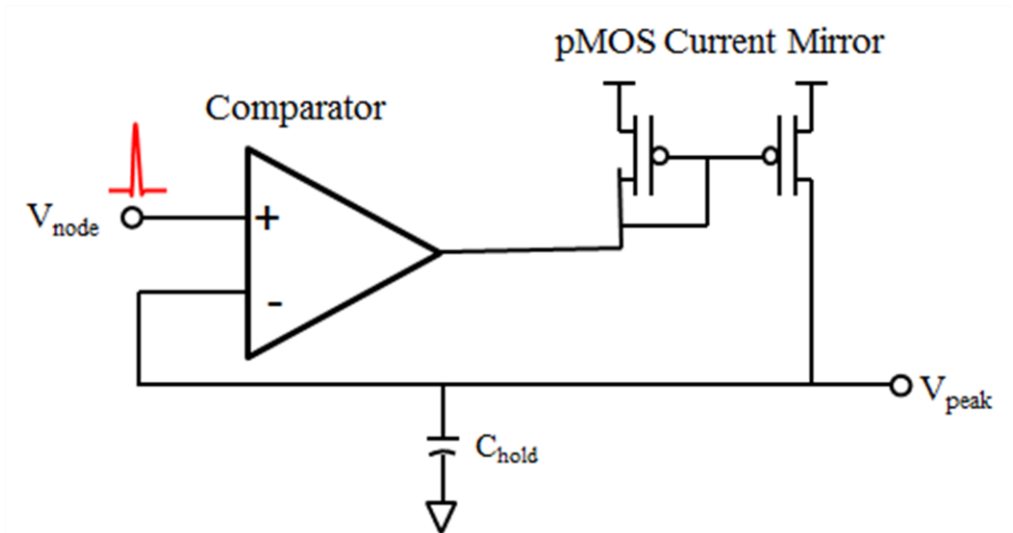


Figure 10: CMOS peak detect and hold circuit

of the current mirror makes it a suitable rectifying element.

The PDH circuit shown above detects and holds rising voltage peaks or transients. When the V_{node} (from the hit transistor) is greater than the output voltage, the differential amplifier (which is in an inverting configuration) changes to logic ‘0’ state and this turns on the pMOS current mirror to charge the hold capacitor (C_{hold}). At this point, the circuit is said to be in the

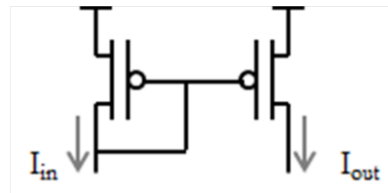


Figure 11: pMOS current mirror as a rectifying element

‘track’ mode i.e., it tracks the peak of the voltage transient. When the V_{peak} attains the peak value and becomes lower than the output voltage (V_{node}), the diff-amplifier switches to logic ‘1’ state and this turns off the current mirror. Thus, the voltage is held across the hit capacitor and the circuit is now said to be in the ‘hold’ mode. Figure 12 explains the different modes of operation

of PDH circuit. It shows a rising V_{node} that is initially tracked and then held across the capacitor during the ‘hold’ mode.

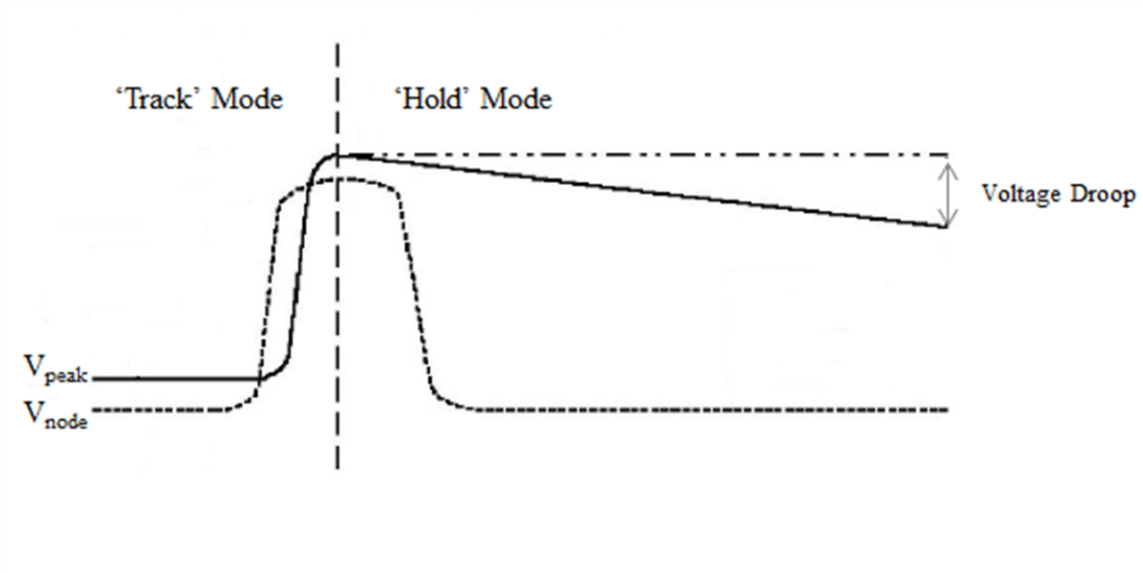


Figure 12: Basic operation of the PDH circuit

The transistor-level schematic of the PDH circuit is shown in the Figure 13. The transistors Mn1, Mn2, Mp1, and Mp2 form nMOS and pMOS differential pairs for the full-swing differential amplifier circuit design respectively. The design of the full-swing high-speed differential amplifier will be discussed in detail shortly. Mp6 and Mp7 form the pMOS current mirror and Mn5 forms the reset switch to reset the capacitor voltage (C_{hold}) prior to making measurement.

Digital-to-Analog Converter (DAC) Design

The block diagram of a simple digital-to-analog converter (DAC) is shown in the Figure 14. An n-bit digital voltage is mapped into a single analog voltage. Typically, DAC’s output is a voltage that is some fraction of reference voltage such that

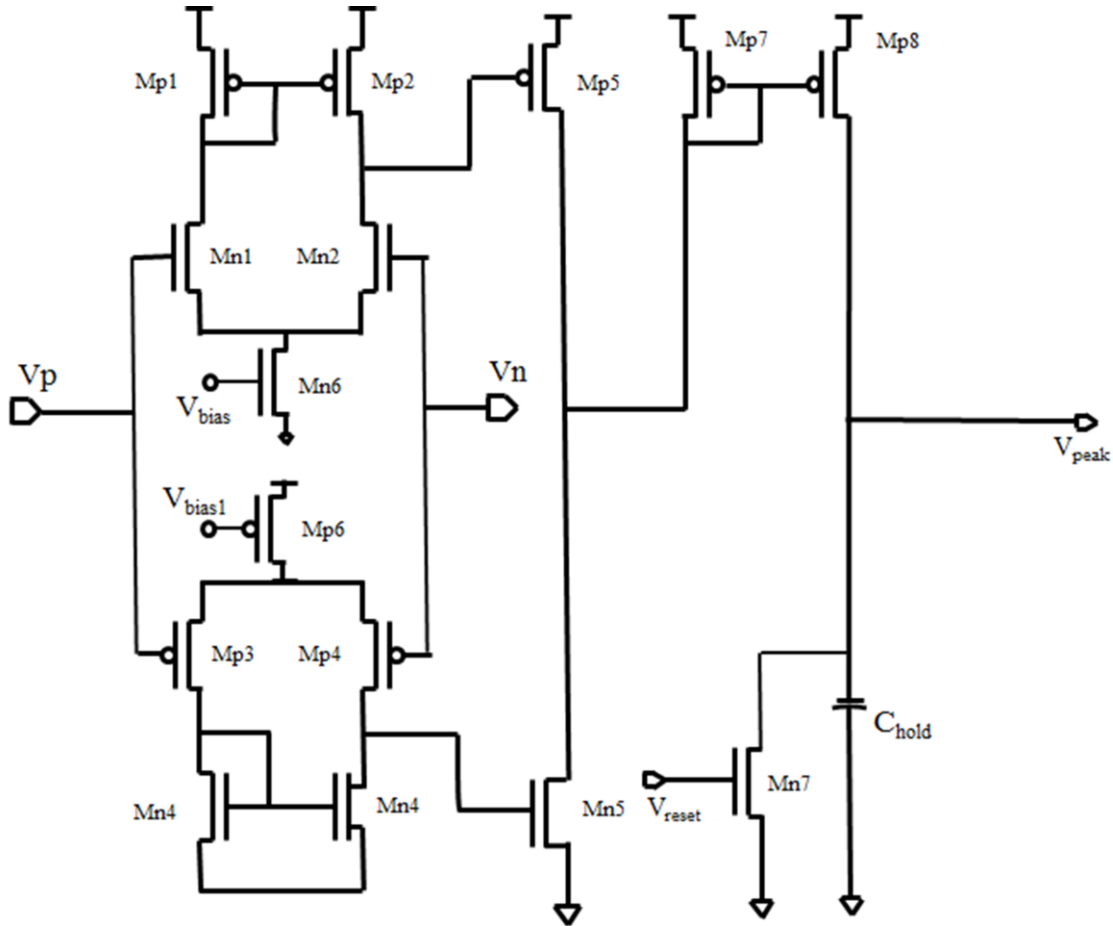


Figure 13: Transistor level schematic of CMOS based peak detect and hold circuit

$$V_{out} = F \bullet V_{ref}$$

where V_{out} is the DAC output voltage and V_{ref} is reference voltage and F is the fraction defined by the input word D , that is N bits wide. The number of input combinations represented by the digital input word D is related to number of bits in the word by

$$\text{Number of input combinations} = 2^N$$

For instance, a 4-bit DAC has a total of 16 input combinations. A converter with a 4-bit resolution maps a change in analog output as 1 part in 16. If the input is a N -bit word, then F is estimated by

$$F = D/2^N$$

A wide variety of DAC architectures exist where some use voltage division, while others employ current steering or charge scaling to map the digital input word to an analog quantity. The

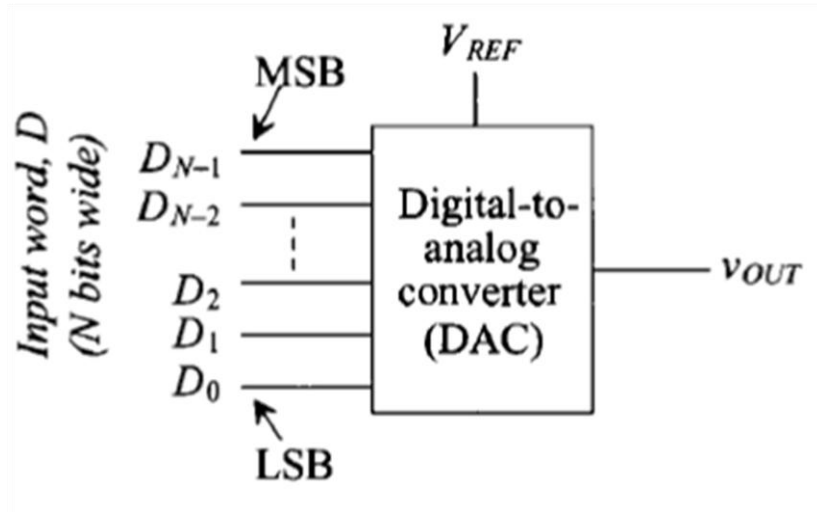


Figure 14: Block diagram of digital-to-analog converter

architecture chosen for the charge collection measurement is that of a 4-bit charge scaling DAC, one of the popular DAC architectures used in CMOS technology and is shown in the Figure 15.

It includes a parallel array of binary weighted capacitors totaling $2^N C$ connected to an op-amp. The value of the capacitance C could be of any desired value. The nMOS transistor is used as a reset switch to initially discharge all capacitors to ground. After initially being discharged, depending on the digital input word, the capacitors are charged to either V_{ref} or ground, causing the output voltage V_{DAC} to be a function of voltage division between the capacitors. For example, Figure 16 shows equivalent circuit of the DAC with MSB ‘high’ and all other bits ‘low’. Since the total capacitor array equals $2^N C$, for the circuit shown below, voltage division

occurs between the MSB capacitor and the rest of the array. Thus, the analog output voltage V_{out} becomes

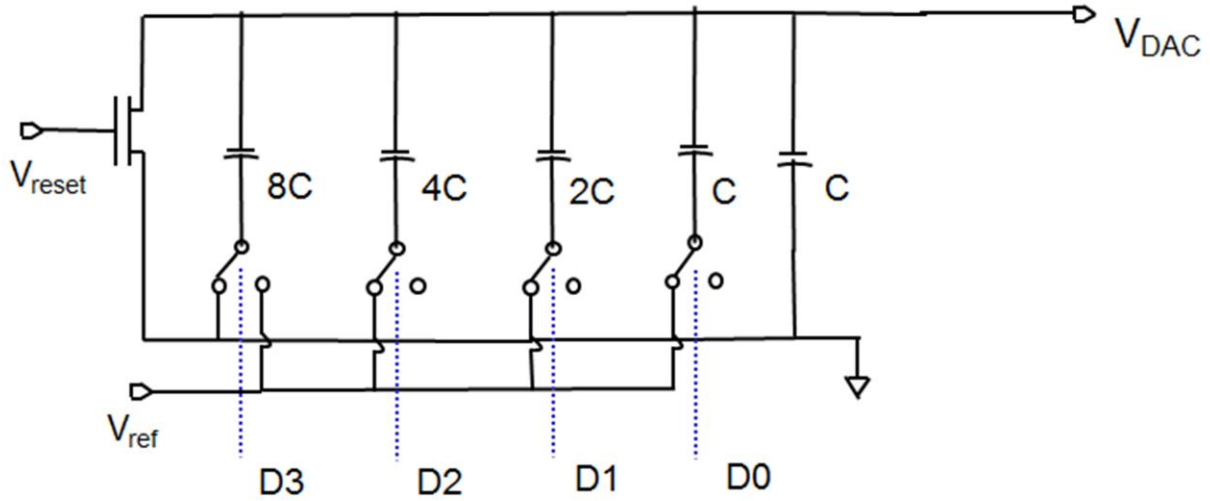


Figure 15: 4-bit Charge scaling DAC architecture

$$V_{out} = V_{ref} * 8 * C / (8 + 4 + 2 + 1 + 1) C = V_{ref} / 2$$

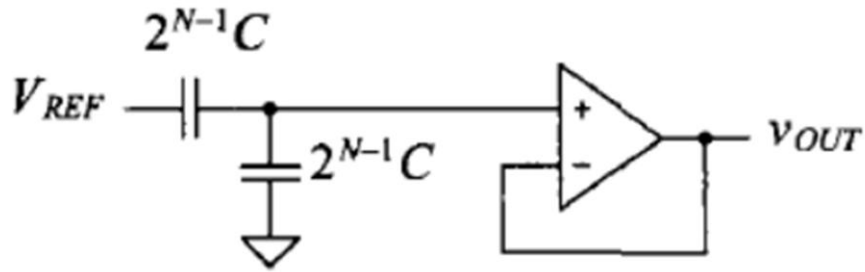


Figure 16: Equivalent circuit of a 4-bit DAC with MSB ‘high’ and the remaining bits ‘low’
 For the circuit in this work, capacitance (C) of 50 fF is used. Since the capacitor array is either charged or discharged by the switches, the value of C is chosen in accordance with

$$I \bullet \Delta t = C \bullet \Delta V$$

where I denotes current flow through the capacitor, ΔV represents change in the voltage across C , and Δt denotes the time required to charge the capacitance.

The voltage buffer amplifier shown on the schematic (i.e., Figure 15) is used to transfer voltage from the first circuit with a high output impedance to a second circuit with a low input impedance. Typically, this is done to prevent the second circuit from loading the DAC circuit which is undesirable. This unity gain buffer could be implemented either by – (1) applying a full negative feedback to an op-amp by connecting its output to its inverting input while the DAC output applied to its non-inverting input. This connection forces the op-amp to adjust its output voltage equal to the input voltage, or (2) MOS transistor in common drain configuration acts a unity gain voltage follower. However, for the charge measurement circuit designed as part of this thesis, the performance of DAC was not affected by its driving circuit (i.e., inverting comparator) and if desired, single transistor voltage follower (common drain configuration of MOS) could be considered as a voltage buffer for the DAC.

Differential Amplifier Design

The circuit shown in the Figure 17 is a basic comparator or decision making circuit. If the voltage across the positive terminal V_p is at a greater potential compared to that of negative

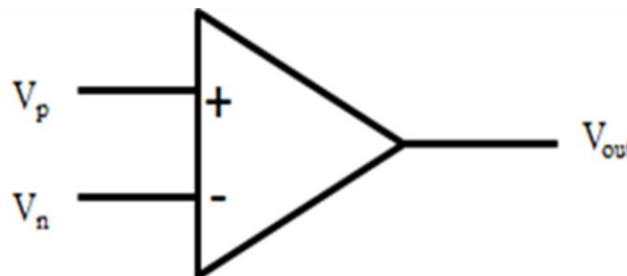


Figure 17: Schematic of a comparator circuit

terminal V_n , the output of the comparator is at a logic '1' state and on the other hand, if V_p is at a lesser potential compared to that of V_n , its output switches to logic '0' state. A simple single-ended differential amplifier design employing diode connected pMOS loads and nMOS differential pair is shown in Figure 18. Its basic operation can be explained as follows – If V_p is more negative than V_n , Mn1 is 'off', Mn2 is 'on' and $I_{d2} = I_{ss}$, $V_{out} = V_{ss}$. As V_p is brought closer to V_n , Mn1 gradually turns on, drawing a fraction of I_{ss} and lowering V_{out} . Now, as V_p becomes sufficiently more positive compared to V_n , Mn1 draws all of the I_{ss} , turning 'off' Mn2 and this in turn results in $V_{out} = V_{dd}$.

There are a few limitations associated with this differential amplifier configuration – (1) input voltage swing is limited by threshold voltage of nMOS transistors (Mn1 and Mn2) and (2) minimum propagation delay for the output to change logic states from the time the differential signals are applied, i.e., the speed of operation of the circuit. To achieve a full input voltage swing and high-speed differential operation, previous researchers showed improved configurations of the design [50]. One such modified configuration of the differential amplifier used for charge collection measurement is shown in the Figure 19.

This differential-amplifier is designed in two stages. The first stage includes a complementary nMOS and pMOS diff-amp pair to achieve rail-to-rail input voltage swing while

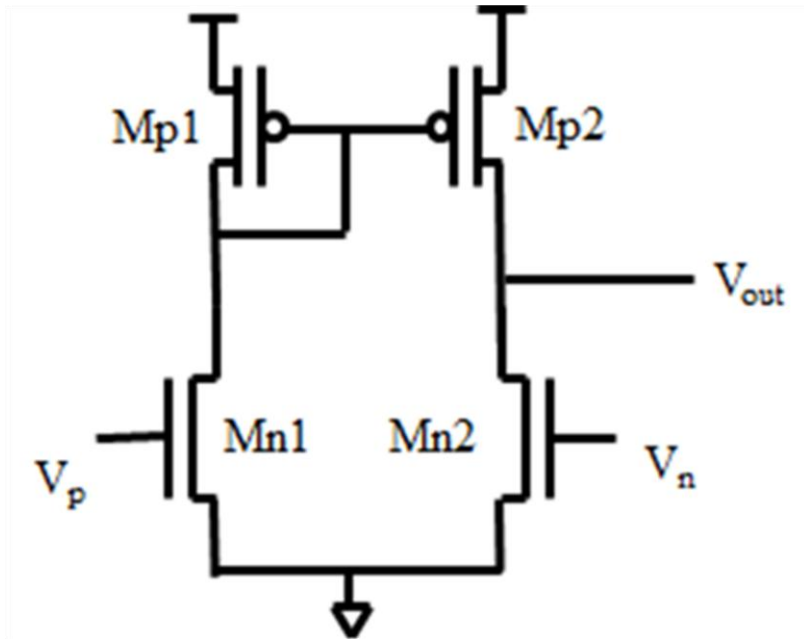
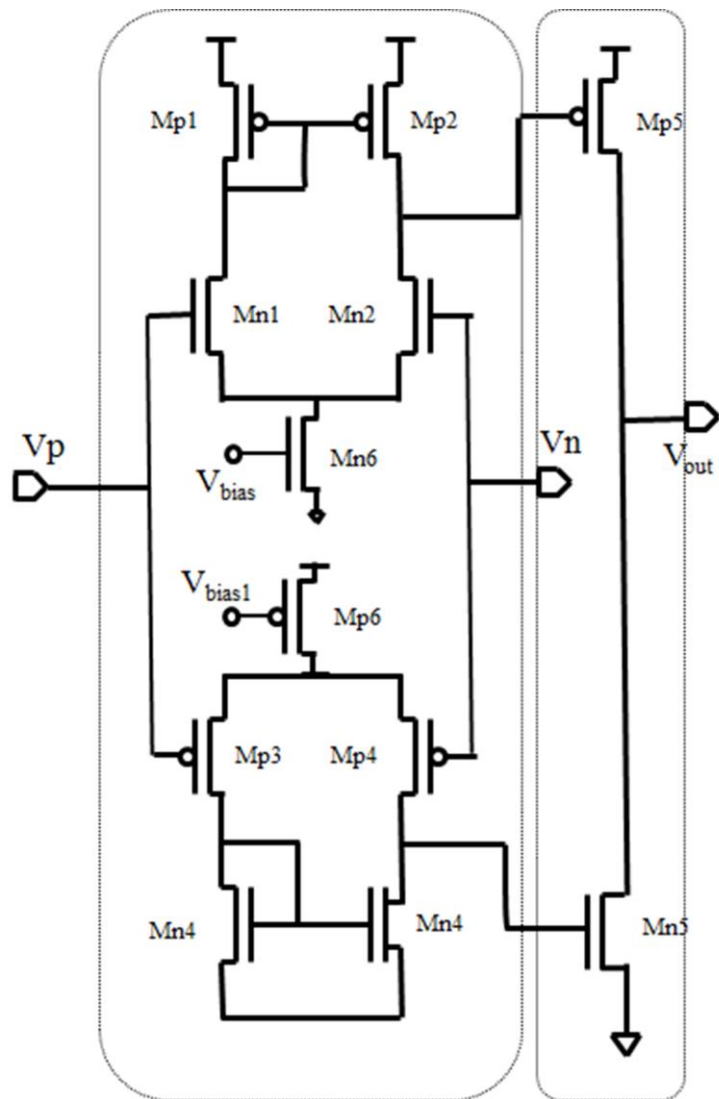


Figure 18: A differential amplifier with diode connected pMOS loads

the second stage includes Mp5 and Mn5 in the common source configuration to achieve high gain and speed. The performance of individual circuit blocks and the overall measurement circuit will be discussed through SPICE simulation results in the subsequent sections.



CHAPTER IV

SIMULATION RESULTS

Simulations were performed in 40 nm UMC Technology using Cadence Spectre simulator [51]. The Spectre is a modern circuit simulator that uses direct methods to simulate analog and digital circuits at the differential equation level. The basic capabilities of the Spice circuit simulator are similar in function and application to SPICE.

Performance of the 4-bit Digital-to-Analog Converter Design (DAC)

Pspice simulations were performed to evaluate the performance of 4-bit DAC. The value of the

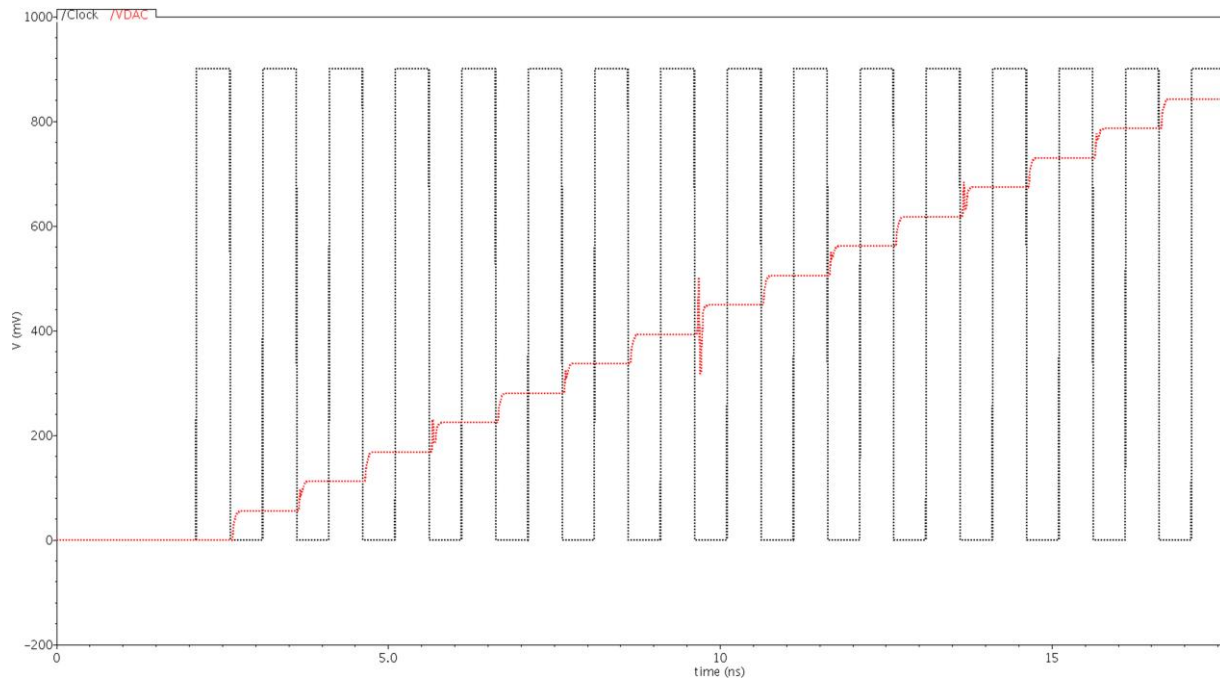


Figure 20: DAC response to digital input word on every clock cycle

binary weighted capacitance (C) used for simulations is 50 fF. The DAC output in response to the 4-bit digital inputs is shown in the Figure 20. The digital input word is applied to the DAC through a counter and its clock waveform is as shown in the figure above. On every clock cycle, the DAC's output voltage is represented by the waveform in blue color.

For a reference voltage of 0.9V, the plot shows that the DAC output voltage increments in steps of 56.25 mV and this is described as 'resolution' of the data converter. Typical specifications of this design are described below –

Offset error

Typically, the DAC output voltage for input word $D = 0$ should be 0. However, due to non-idealities, there is offset voltage associated with the design even when $D = 0$. For the design used in our work, the offset voltage is estimated to be 0.25 LSB.

Differential non-linearity error (DNL error)

Ideally, each adjacent output increment should be exactly one sixteenth (for a 4-bit DAC) of the reference voltage. Thus, each ideal increment corresponds to 1 LSB, i.e., 56.25 mV. However, non-ideal components cause the analog increments to differ from their ideal values. This difference between ideal height of increment and the actual incremental height is defined as differential non-linearity

$$\text{Differential Non-Linearity (DNL}_n\text{)} = \text{Ideal height of transition} - \text{actual height}$$

Where 'n' corresponds to the digital input. This specification is measure of how accurately the DAC can generate uniform analog LSB multiples at its output. The DNL for the entire converter is calculated to be - 0.0019 LSB

Gain Error

For a non-ideal DAC, a gain error exists if the slope of the transfer curve obtained from simulating DAC is different from the slope of the best-fit line for the ideal DAC. This design has a gain error of 0.04 LSB

The circuit simulations are carried out using a 4-bit DAC and the design-tradeoffs associated with further implementing the charge collection measurement circuit design using higher-order DAC circuit designs are discussed in the design trade-offs section.

Performance of differential amplifier (inverting comparator)

The inverting comparator design as discussed in the previous section is simulated to characterize its performance. The transistor sizes are as listed in the Table I. The transistors Mn1, Mn2 (nMOS diff-pair) and Mp1, Mp2 (pMOS diff-pair) are sized to set the diff-amp transconductance (g_m , sets the gain of the stage) as well as the input capacitance. The pMOS and nMOS current mirror loads are sized to match the bias currents set by the diff-pairs. The transistors Mp5, and Mn5 are sized to achieve high gain and increased speed of operation. The design procedure could be iterated with these equations -

Differential voltage gain of the diff-amp (A_v) = $g_{m1} (r_{on2} \parallel r_{on4})$ or $g_{m1}/(g_{ds2} + g_{ds4})$

Maximum common mode voltage ($V_{IC(max)}$) = $V_{dd} - V_{sg3} + V_{tn1}$

Minimum common mode voltage ($V_{IC(min)}$) = $V_{ss} + V_{ds5(sat)} + V_{gsn1}$

It is desirable for the circuit to have a wide common-mode range which is the range of voltage over which the differential-amplifier continues to sense and amplify the differential inputs with the same gain. The detailed calculations to determine the transistor sizes are shown below by

considering the case of nMOS diff-amp pair with pMOS current mirror loads. The same applies to its complementary diff-pair i.e., the pMOS diff pair with nMOS current mirror load.

$$(1) V_{IC(max)} = V_{dd} - V_{sg3} + V_{tn1}, \text{ for a } V_{IC(max)} = 800 \text{ mV}$$

$$800 \text{ mV} = 900 \text{ mV} - V_{sg3} + 280 \text{ mV}$$

$$V_{sg3} = 380 \text{ mV} = \sqrt{(2 \cdot I_{ss} / (K_n \cdot (W_3/L_3)))} + V_{tn3}, \text{ for } I_{ss} \text{ of } 50 \text{ uA hand calculations suggest } (W_3/L_3) = (W_4/L_4) = \sim 30$$

(2) Keeping the tail-current fixed, it is desirable to calculate the transistor sizes of M_{n1} and M_{n2} and they are determined from the gain equation given by -

$$A_v = g_{m1} / (g_{ds2} + g_{ds4}) = (\sqrt{(2 \cdot K_{n1} \cdot (W_1/L_1))} / (\lambda_{dp} + \lambda_{dn}) \sqrt{I_{ss}}), \text{ where } \lambda \text{ is the channel length modulation parameter, } I_{ss} = 50 \text{ uA.}$$

Initially, gain of ~ 70 is assumed and this may be altered depending upon the (W_1/L_1) obtained. Substituting the values in the gain equation above gives $(W_1/L_1) = \sim 15$. The upper limit on the chosen gain is to pick W_1/L_1 such that the input capacitances are lower.

(3) Now, the tail-bias current transistor sizes are determined from the minimum common mode voltage equation given by –

$$V_{IC(min)} = V_{ss} + V_{ds5(sat)} + V_{gsn1}, \text{ for a } V_{IC(min)} = \sim 1/2 \cdot V_{dd} \text{ (i.e., } 500 \text{ mV)}$$

$$V_{ds5(sat)} = 500 \text{ mV} - \sqrt{(2 \cdot I_{ss} / K_n \cdot (W_1/L_1))} - V_{tn1}, \text{ for } I_{ss} = 50 \text{ uA, } W_1/L_1 = 15 \text{ calculations suggest a } V_{ds(sat)} \text{ of } \sim 200 \text{ mV. From this, } (W_5/L_5) \text{ is obtained by –}$$

$$W_5/L_5 = (2 \cdot I_{ss}) / (K_n \cdot V_{ds(sat)}^2) = \sim 35$$

From the $V_{ds(sat)}$, V_{bias} for the tail current source i.e., V_{gs5} is fixed $\sim 400 \text{ mV}$

From the design, the common mode range is extended on the lower limit through the pMOS diff-amp and its calculations are similar to the equations described above for the nMOS diff-pair

Transistor Type	Length (nm)	Width (um)
Mn1, Mn2	50	0.655
Mn3, Mn4	230	3.12
Mp1, Mp2	230	3.12
Mp3, Mp4	230	1.2
Mp5, Mp6	50	3.12
Mn5, Mn6	50	3.12

Table I: Widths and Lengths of transistors used for the 40nm technology design

Transient Response

Considering $V_p = 400$ mV ($V_{dd}/2$) and V_n to be a 2 ns wide pulse whose amplitude varies from

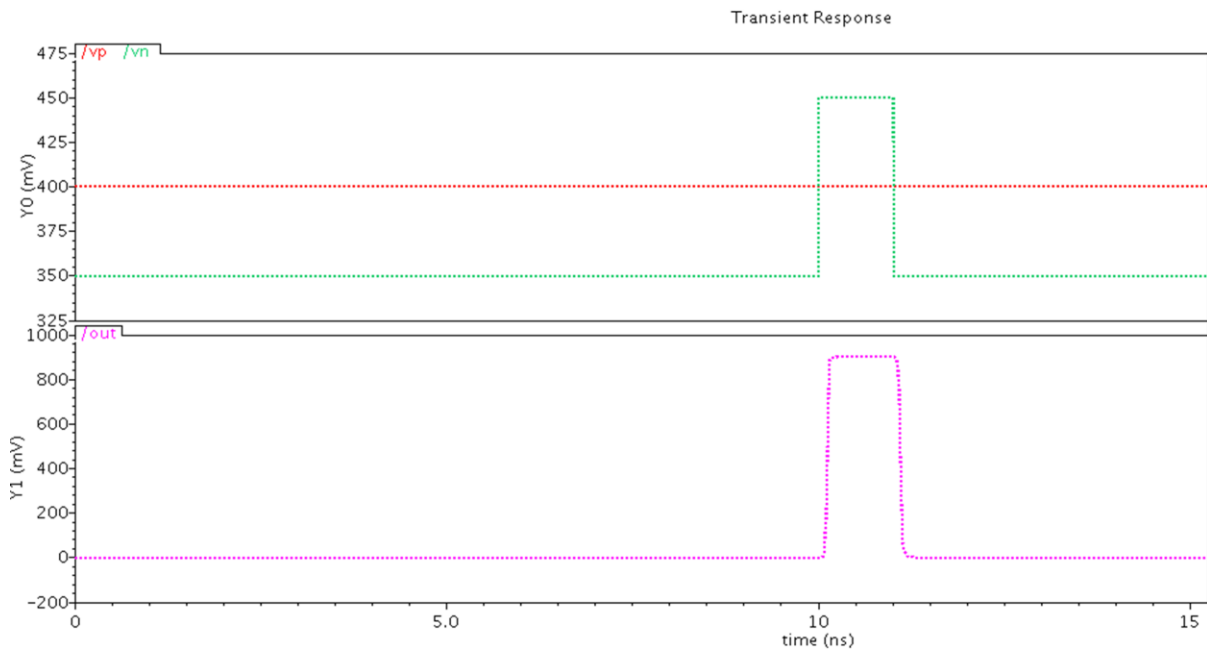


Figure 21 (a) & (b): (a) output waveform of the comparator (b) Transient response of the

350 mV to 450 mV, i.e., the positive terminal is 50 mV above the negative input. The transient response of the comparator with these inputs is as shown in the Figure 21 (a) & (b).

Propagation Delay

Ideally, propagation delay defined as the time difference between the input V_p crossing the reference voltage V_n and the output changing logic states is zero. However, the maximum propagation delay for this design is calculated to be 300 ps.

Peak Detect and Hold Circuit Performance

The transistor sizes used in the design of the circuit are as listed in the Table II. The comparator used for PDH circuit design is exactly similar to the comparator design discussed in the earlier section and the design equations to determine the transistor sizes for the differential amplifier are also as discussed in the earlier section. The pMOS transistors (Mp7, Mp8) of the current mirror are minimally sized (for a given technology) transistors. Minimal sized transistors are desirable to reduce the leakage due to the current mirror during the ‘hold’ mode (which results in ‘positive voltage droop’). For the chosen width (W) and length (L) of pMOS current mirrors, the leakage current is estimated to be ~5 nA. This is estimated from the leakage current equations -

$$I_{\text{off}} (\text{nA}) = I_o (W/L) e^{q(v_{\text{gs}} - v_t)/KT}$$

Similarly, the nMOS reset switch (Mn7) is sized to compensate for the leakage current estimated above. This is done to minimize the ‘voltage droop’ due to the nMOS transistor. In the circuit designed, although the positive and the negative voltage droops are reduced by sizing W/L, the pMOS current mirror still results in a worst-case ‘droop’ of 150 uV/ usec. The value of the hold

capacitor is determined by the range of expected charge collected which in this case is chosen to be 100 fF (to account up to ~90 fC of collected charge)

Transistor Type	Length (nm)	Width (um)
Mn1, Mn2	50	0.655
Mn3, Mn4	50	3.12
Mp1, Mp2	230	3.12
Mp3, Mp4	230	1.5
Mp5, Mp6	50	3.12
Mn5, Mn6	50	3.12
Mp7, Mp8	50	1.5
Mn7	50	0.4

Table II: Widths and lengths of the transistors used for PDH circuit design

Simulations results shown in the Figure 22 include the peak detected voltage for a peak voltage of 600 mV. Results indicate that voltage droop is about 150 uV/ usec and the maximum peak detection voltage offset/error is ± 25 mV (this is not observed in the plot).

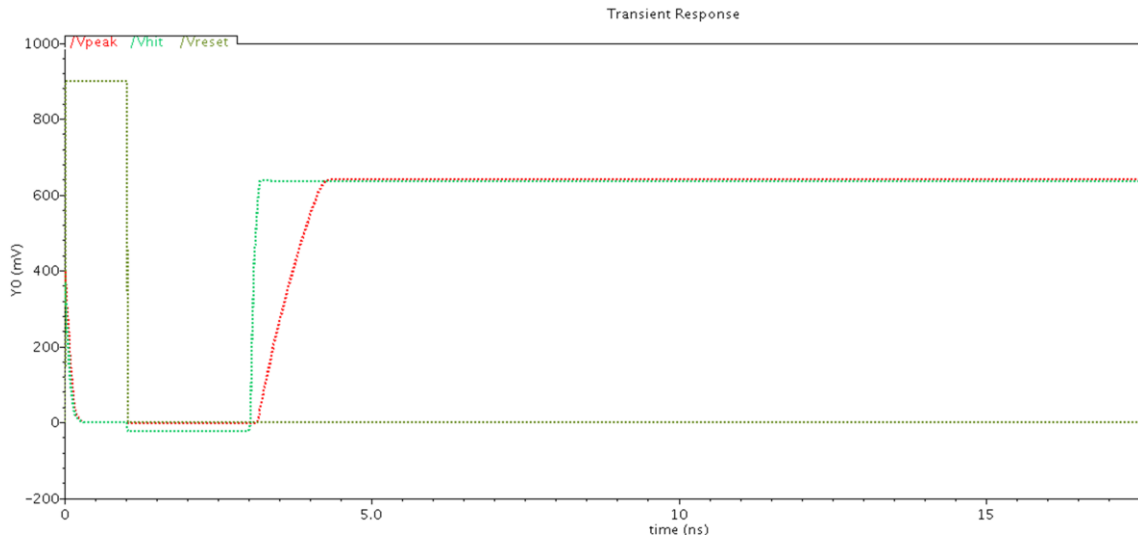


Figure 22: Peak detected voltage in response to a voltage transient on a single 'OFF' pMOS transistor

The plot shows a V_{reset} pulse applied for a period of 1 ns to discharge the hold capacitor prior to an ion-strike on the ‘OFF’ pMOS transistor. V_{hit} shown in the plot (the curve shown in ‘green’ color) shows a change in the node voltage of the ‘hit’ transistor due to an ion-strike (the transient is modeled as a bias-dependent single-event model). After an ion-strike, a change in the node voltage is detected and held by the PDH circuit which is as shown in the Figure 22.

Charge Collection Measurement Circuit

The test structure (a nominal V_t ‘OFF’ pMOS device) with a 100 fF capacitor was simulated for charge collection measurements. A bias-dependent single-event model [45] was used to simulate the transient generated due to an ion-strike. This model was recently developed to capture the dynamic charge collection interactions represented in TCAD. The development of this model was based on the fact that charge collection dynamically interacts with the circuit response. The interested reader is directed to [52] for further details on the model.

Table III shows the results of charge collection measurements as a result of ion-strikes on the test structure. These simulations were carried out at a nominal supply voltage of 900 mV and the counter operating at 1 GHz. From the table, V_{node} represents the change in the voltage due to the

V_{node} (mV)	V_{peak} (mV)	Counter Value (C)	$V_{\text{measured}}[\text{C} * \text{DAC}_{\text{resolution}}]$ (mV)
358.7	368.9	0111	393.75
440.6	441	1000	450
526.3	519	1001	506.2
612	595	1011	618.75
672.2	660.5	1100	675
789.4	759.8	1101	787.5

Table III: Voltage transient measurements due to an ion-strike on an ‘OFF’ pMOS

strike on the circuit node and V_{peak} is the peak value of the voltage captured by the PDH circuit. V_{measured} calculated from the counter output represents the hit voltage measured by the circuit. Based on the counter value seen at the circuit output, V_{measured} is calculated from the DAC resolution as –

$$V_{\text{measured}} = \text{Counter output} \times \text{DAC}_{\text{resolution}}$$

Now, the charge collected is calculated as the nodal capacitance times the voltage measured across the hit node - $Q_{\text{measured}} = C * V_{\text{measured}}$

Q_{node} (fC)	Counter Value (C)	Q_{measured} [C * $\text{DAC}_{\text{resolution}}$] (fC)
35.87	0111	39.37
44.06	1000	45
52.63	1001	50.62
61.2	1011	61.87
67.22	1100	67.5
78.94	1101	78.75

Table IV: Charge collected on the hit transistor due to an ion-strike

Table IV shows the calculated values of charge collected for a capacitance size of 100 fF and a supply voltage of 900 mV. The circuit resolution is calculated to be 5 fC which is determined by the DAC resolution (56.25 mV for the 4-bit DAC used in this circuit). However, there is a voltage offset/ error associated with the circuit which is defined as the difference between the actual hit node voltage (V_{node}) and the measured output voltage of the DAC (V_{DAC}) and this worst-case voltage error is estimated to be ± 1 LSB (where 1 LSB = 56.25 mV (or) 5 fC).

Impact of Supply Voltage Variation

Variations in the supply voltage can cause variations in the circuit performance. Simulations were carried out to characterize the circuit performance for a $\pm 10\%$ variation in the supply voltage. Figure 23 shows a plot of charge collected on the hit transistor for a range of supply voltage values of 810, 900, and 990 mV respectively. While the black line represents ideal linear relationship between the actual and measured values, the red curves represent the measurements at different supply voltages. It is observed that for a $\pm 10\%$ voltage variation, the minimum offset/ voltage error is estimated to be within ± 1 LSB (1 LSB = 56.25 mV (or) 5 fC). To reduce the circuit sensitivity to supply variations and improve its accuracy of measurement, on-chip decoupling capacitors are connected between supply and the ground. The added capacitor not only filters out any ac fluctuations that appear on the supply rail but also supplies the needed charge during the transient times. Hence, it keeps the voltage applied across the circuit at Vdd. Hand calculations suggest that the amount of decoupling capacitance required to suppress a \pm

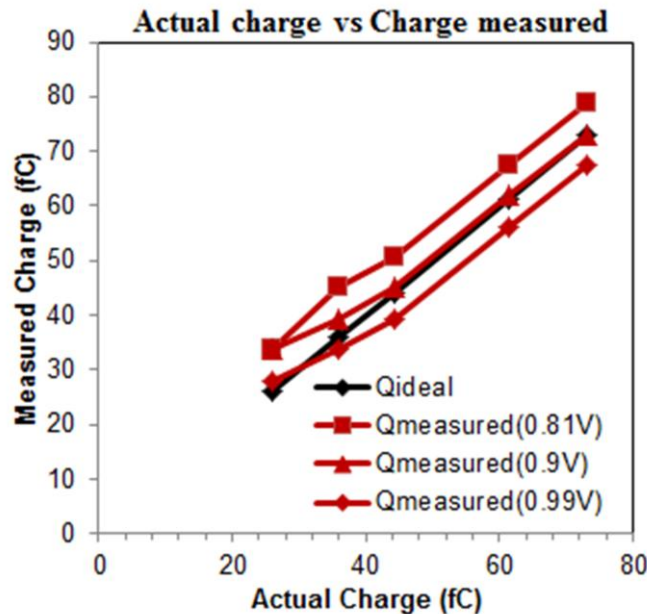


Figure 23: Charge collected on the hit node for a range of supply voltages 810, 900, and 990 mV

10% variation on Vdd lines is ~ 20 pF. As such high values are not practical on-chip, off-chip capacitors are used across the power and ground pins.

Impact of process variations

Variations in the manufacturing process parameters result in large shifts in individual transistor parameters and affect the circuit response. These variations include gate depletion [53], surface state charge [54], line edge roughness [55], random dopant fluctuations [56-57] and so on. Process variations can cause large variations in chip-level parameters such as standby leakage current (due to variations in the channel length and threshold voltage) and operating frequency. Hence, process- and transistor- parameter variations pose a serious challenge for circuit design at advanced technology nodes.

For semiconductor fabrication, process corners represent a six sigma variation from nominal doping concentrations and other parameters in transistors on a silicon wafer. This variation can cause significant changes in the circuit performance. To characterize the circuit performance for process variations, simulations were performed at four different process corners – (1) fast nMOS and fast pMOS (referred to as ‘ff’ process corner) (2) slow nMOS and slow pMOS (also referred to as ‘ss’ process corner) (3) fast nMOS and slow pMOS (the ‘fnsp’ process corner) and finally (4) slow nMOS and fast pMOS (‘snfp’ process corner). The first two corners are referred to as even corners because both n- and p-FETS are equally affected and this generally does not adversely affect the logical correctness of the circuit. On the other hand, the last two corners are referred to as skewed corners because one type of device switches faster than the other. Figures 24-25 show the measurements obtained at even process corners.

The circuit resolution remains ~ 5 fC (same as that obtained for a 'tt' corner). While the worst-case voltage error at a 'ff' corner remains within ± 1 LSB (where 1 LSB as defined earlier is ~ 5 fC), for a 'ss' process corner the voltage error is estimated to be ± 1.88 LSB. Similarly at skewed process corners, there is a voltage error of ± 1 LSB. Figure 26 shows the measurements obtained at skewed corners.

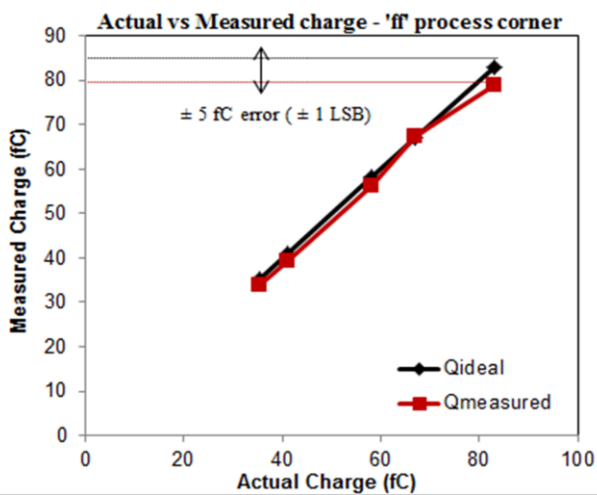


Figure 24: Charge collection measurements on an 'off' pMOS device ('ff' process corner)

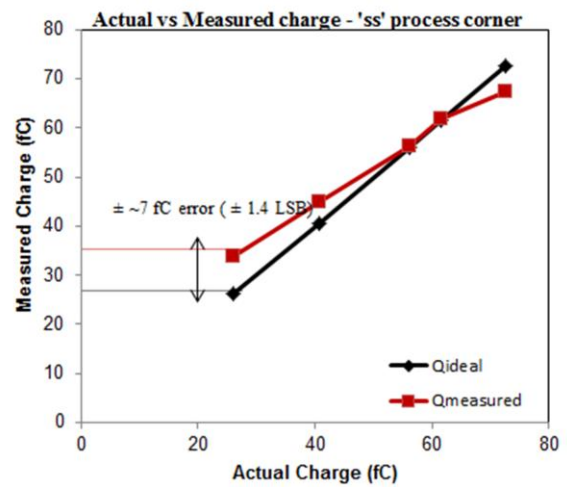


Figure 25: Charge collection measurements on an 'off' pMOS device ('ss' process corner)

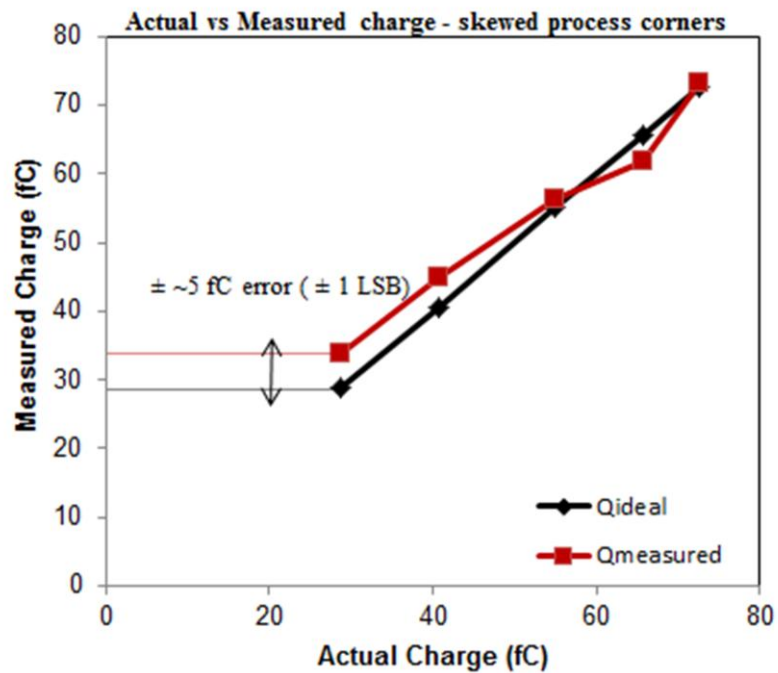


Figure 26: Charge collection measurements on an 'off' pMOS device (skewed corners)

Design Trade-offs and Considerations

Although the measurement circuit using a 4-bit DAC has a resolution of ~ 5 fC, certain design considerations to further improve the circuit resolution, such as increasing the DAC size, must be considered before implementing the actual circuit. The following section examines in detail alternative design considerations for the proposed measurement circuit.

On determining DAC size

The resolution of the measurement circuit is determined by the resolution of the DAC. While the 4-bit DAC used in the design has a resolution of 56.25 mV, a 5-bit DAC has an improved DAC resolution of 26.125 mV. Figure 27 shows the charge collection measurements using both 4-bit and 5-bit DAC designs. Simulations show that maximum possible resolution is ~ 2.5 fC compared to ~ 5 fC obtained using a 4-bit DAC (which is not clearly visible in the plot). However, the plot shows reduced voltage error from ± 1 LSB (for a 4-bit DAC) to ± 0.5 LSB

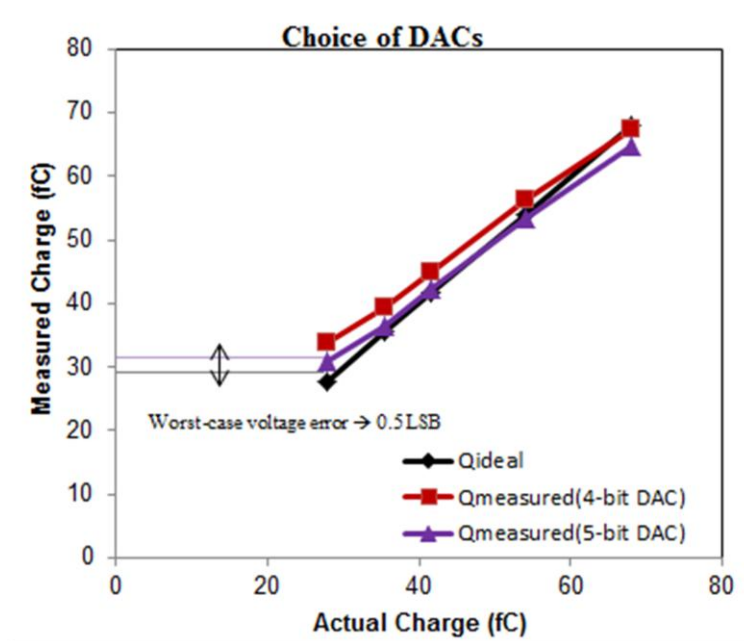


Figure 27: Charge collection measurements on an 'off' pMOS device using 4-bit and 5-bit DAC

(for a 5-bit DAC). Thus, implementing higher order DACs means higher resolution and reduced voltage errors. But, there is an upper limit on the DAC size that could be used for the measurement circuit which is primarily based on the accuracy at which the PDH circuit detects and holds V_{peak} . The maximum voltage error/ offset of the PDH circuit that exceeds 1 LSB (LSB is a unit of DAC resolution) determines the maximum DAC size. Results show that for a PDH circuit that is within ~ 20 mV of voltage offset, a 5-bit DAC would be the optimal DAC size for implementing the charge measurement circuit.

On comparator design

Throughout this work, the circuit design involves two comparators i.e., one used in the design of peak detect and hold circuit (PDH) design and the other to compare the detected peak voltage against the DAC voltage. Since any voltage error induced in the charge collection measurement is due to the non-idealities of these comparator designs, this section briefly analyzes the impact of an ideal comparator design on the accuracy of charge collection measurements. Thus, the comparator design used in the circuit is replaced with an ideal comparator. This ideal comparator is a voltage controlled voltage source obtained from the basic analog library of Cadence. The measurements on a hit transistor are then obtained as shown in the Table V.

V_{node} (mV)	V_{peak} (mV)	Counter Value (C)	$V_{\text{measured}}[C * \text{DAC}_{\text{resolution}}]$ (mV)
358.7	366.6	0111	393.75
440.6	448	1000	450
526.3	534	1010	562.5
612	620	1011	618.75
789.4	794.2	1111	843.75

Table V: Voltage transient measurements due to an ion-strike on an ‘OFF’ pMOS transistor

From the table, it is observed that the worst-case voltage error is 1 LSB. Simulations using ideal comparator suggests that by optimizing the comparator design, it is possible to improve the circuit measurement resolution by implementing the circuit using higher order DAC. For example in this case voltage droop due to the PDH circuit is 8 mV (as observed from the Table V) and hence a 7-bit DAC (optimal size) could be implemented to allow a measurement resolution of ~ 1.4 fC of charge (since 1 LSB for a 7-bit DAC = 14 mV).

Capacitor calibration

In order to calibrate the value of capacitance used for the charge measurement, there are various methods that may be considered. One of them is based on the basic equation for charge on a capacitor [58] given by –

$$Q = C \cdot V$$

where Q is the charge on the capacitor, C is the capacitance value, and V is the voltage across the capacitor. If the charge deposited on a capacitor, and the resultant voltage across the capacitor are known, the value of the capacitor can be estimated using the above equation. A simple circuit that uses the above principle is shown in Fig. 28. Here, a large resistor is used to charge the voltage across a capacitor, C_x , whose value is to be determined. C_{pad} is the parasitic capacitance associated with the circuit node as shown in the Fig. 28.

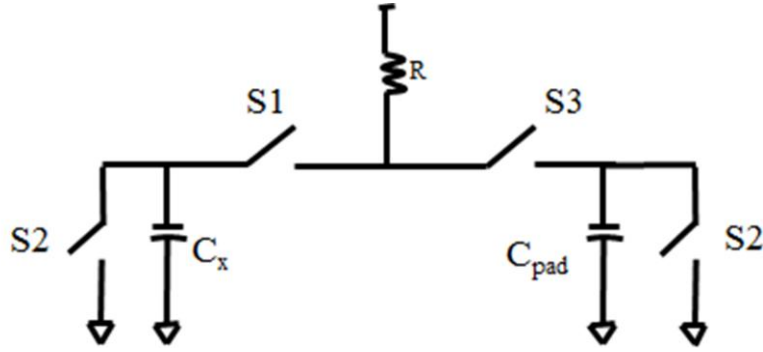


Figure 28: charge based capacitance measurement method.

The circuit initial conditions are such that switch S2 is closed and hence both C_x and C_{pad} are discharged to ground i.e., initial voltage across C_x and C_{pad} is 0 volts. Initially, switch S2 is opened and then switch S3 is closed. After a known time period, capacitor C_{pad} is charged upto a known voltage V_{x1} . Now, switch S1 is closed while keeping S3 closed until C_x is charged upto a known voltage V_{x2} . The following equations may be used to determine the total amount of charge in the circuit before and after switches S1 and S3 remain closed.

$$\text{Initial charge in the circuit} - Q1 = C_{pad} \cdot V_{x1}$$

$$\text{Final Charge in the circuit} - Q2 = C_{pad} \cdot V_{x2} + C_x \cdot V_{x2}$$

The difference in total charge stored in the circuit must have come from supply line through the resistor, i.e.,

$$\int I \cdot dt = (Q2 - Q1) = C_{pad} \cdot V_{x2} + C_x \cdot V_{x2} - C_{pad} \cdot V_{x1} = \int (V_{dd} - V_{out}(t)) / R \cdot dt$$

For sufficiently large values of resistors, the time-dependent voltage waveform can be captured using an oscilloscope. Once this waveform is known, the total amount of charge required to charge the unknown capacitor, C_x , to V_{x2} is known. Using the above equation, the unknown

value of the capacitor then can be calculated. – The CMOS based schematic is as shown in the Figure 29.

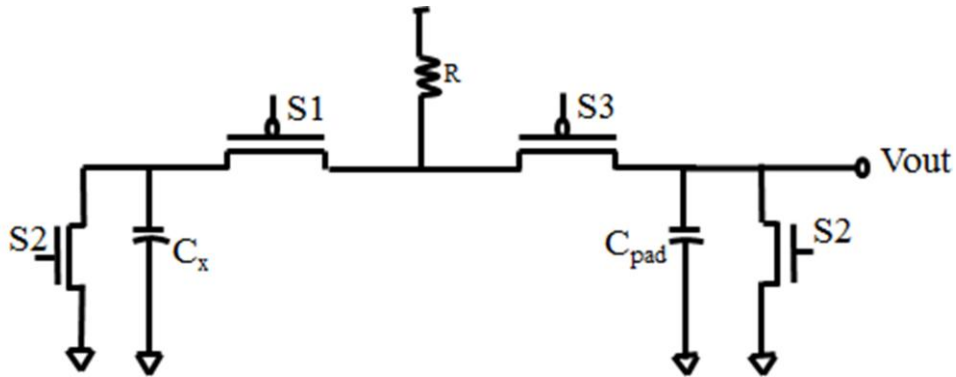


Figure 29: Transistor level schematic of charge based capacitance measurement method

The input signals S1, S2 and S3 may be applied externally or on-chip with the requirement that they are non-overlapping. S1 and S3 must also stay closed for long enough period to charge C_x to V_{x2} .

Circuit-level simulations were carried out to estimate the value of an unknown capacitor. The value of R used was 200K, the value of C_{pad} used was 1 pF and the value of C_x used was ~300 fF. Fig. 30 shows simulation results for V_{out} as a function of time.

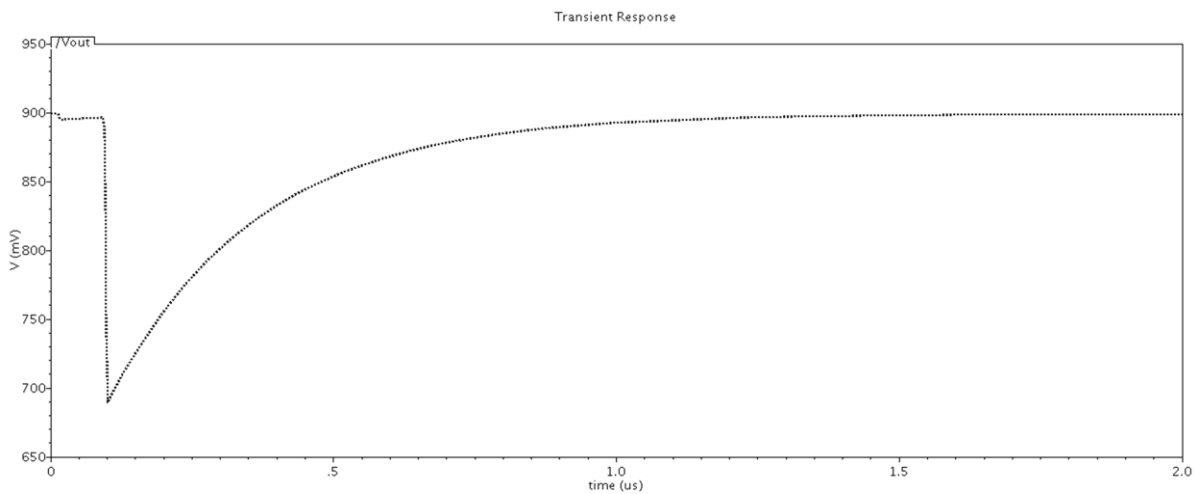


Figure 30: The output waveform of V_{out}

Based on this waveform and the equation given above, the value of the C_x capacitor was estimated to be ~311 fF given by –

$$\text{From, } \int I \cdot dt = (Q_2 - Q_1) = (C_{\text{pad}} + C_x)V_{x2} - C_{\text{pad}} \cdot V_{x1} = C_x \cdot V_{x1} \text{ (since } V_{x1} = V_{x2} \text{ here)}$$

where I denotes the current flowing to charge the capacitor until V_{out} reaches 0.85 V ($V_{x1} = V_{x2} = 0.85$ V here) and is given by

$$I = C_{\text{pad}} \cdot dV/dt = 1 \text{ pF} \cdot 0.85 \text{ V} / 1 \text{ us} = 0.9 \text{ uA} \text{ (the capacitor is charged to 0.85 V in 1 us time period)}$$

$\int 0.9 \text{ uA} \cdot 290.1 \text{ ns} = C_x \cdot 0.85 \text{ V}$ and this indicates that C_x is ~308 fF (where 290.1 ns time period indicates the time taken for the capacitors (C_{pad} and C_x) to reach 0.85 V after switches S_1 and S_3 are closed)

This indicates a simulation error of ~2%. This error in the measurement may be attributed to (1) the contribution of parasitic and interconnect capacitances and resistances of nMOS and pMOS transistors, (2) leakage currents associated with the off nMOS transistors providing a leakage path for the capacitances C_x and C_{pad} . When an actual circuit is fabricated, additional parasitic elements (capacitances and resistance) will come into play and affect the measurement accuracy. Since these factors are also dependent on the circuit layout and the technology, care must be taken to generate the layout to minimize the effects of these parasitic elements.

CHAPTER V

CONCLUSION

This thesis describes the implementation of an autonomous charge collection measurement circuit to experimentally characterize charge collection process in advanced technologies. Simulations were performed using the UMC 40 nm process with SE strikes represented by the double-exponential current pulse model. Results show a maximum measurement resolution of ~ 5 fC with a voltage offset of ± 1 LSB. For supply voltage variations of $\sim 10\%$ the circuit shows a minimum voltage error of ± 1 LSB (where $1 \text{ LSB} = 0.056 \text{ V}$ (or) 5 fC) while its resolution still remains 5 fC . Additionally for simulations carried out at different process corners to characterize the circuit for process variations, its voltage offset varied from ± 1.4 LSB (at a 'ss' process corner) to ± 1 LSB (for a 'fnsp' process corner).

Simulations to determine the optimal DAC size that could be used to improve the circuit resolution indicated using a 5-bit DAC for a maximum ~ 2.5 fC resolution. Typically, laser or broad beam experiments are carried out to test the circuit designs. For laser tests, the exact location at which the hit takes place is known and hence the design could be tested using laser. Also, the *self-triggered* circuit technique allows for one-time measurements due to ion-strikes on circuit nodes. Another advantage with the circuit technique is that the voltage measurements are such that user reads out a digital value corresponding to the voltage transient on the circuit node. However, for broad beam experiments information regarding the time and location of the hit node is usually not available and hence it is required that the target sensitive area be much larger

compared to the measurement circuit. Further improvements by considering target structures for broad beam experiments are also possible.

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APPENDIX A

SPIICE NETLIST

This appendix displays the detailed netlist, created using Cadence and the Spectre environment, describing the implementation of autonomous charge collection measurement circuit design and its sub-circuits

```
// Generated for: spectre
// Generated on: Jun 24 15:45:00 2012
// Design library name: charge_measurement
// Design cell name: chargescalingDAC
// Design view name: schematic
simulator lang=spectre
global 0
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_rvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40_momcaps_v041.lib.scs"
section=tt
//////////////////////////////////Beginning of charge scaling DAC//////////////////////////////////
// Library name: charge_measurement
// Cell name: inverter
// View name: schematic
subckt inverter in out vdd vss
    PM0 (out in vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out in vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
ends inverter
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor_8
// View name: schematic
subckt multiplexor_8 in out vdd vss
    I0 (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=8 mf=8 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
```

```

    sca=31.6456 scb=12.4686m scc=2.69597m
PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
sca=35.3357 scb=13.9568m scc=3.02914m
NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
NM0 (out inbar vss vss) n_p9_grvt m=8 mf=8 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_8
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: multiplexor_4
// View name: schematic
subckt multiplexor_4 in out vdd vss
    IO (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=4 mf=4 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
    PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
sca=35.3357 scb=13.9568m scc=3.02914m
    NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out inbar vss vss) n_p9_grvt m=4 mf=4 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_4
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: multiplexor_2
// View name: schematic
subckt multiplexor_2 in out vdd vss
    IO (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=2 mf=2 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
    PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
sca=35.3357 scb=13.9568m scc=3.02914m
    NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \

```

```

    sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out inbar vss vss) n_p9_grvt m=2 mf=2 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_2
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor
// View name: schematic
subckt multiplexor in out vdd vss
    I0 (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
    PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
    as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
    sca=35.3357 scb=13.9568m scc=3.02914m
    NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out inbar vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: chargescalingDAC
// View name: schematic
V0 (vactual vss) vsource type=pwl wave=[ 2.25n 0 2.75n 56m 3.25n 112.5m \
    3.75n 168m 4.25n 225m 4.75n 281.25m 5.25n 337.5m 5.75n 393.75m \
    6.25n 450m 6.75n 506.25m 7.25n 562.5m 7.75n 618.75m 8.25n 675m \
    8.75n 731.25m 9.25n 787.5m 9.75n 843.75m ]
I0 (i3 net29 vdd vss) multiplexor_8
I5 (i2 net25 vdd vss) multiplexor_4
I10 (i1 net17 vdd vss) multiplexor_2
C17 (vout net17 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=2 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
C18 (vout net25 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=4 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
C20 (vout net29 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=8 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
C1 (vout net21 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=1 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
C0 (vout vss) capacitor c=50f

```

```

NM0 (vout vreset vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
  as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
  sca=31.6456 scb=12.4686m scc=2.69597m
I6 (i0 net21 vdd vss) multiplexor
include "./_graphical_stimuli.scs"
simulatorOptions options reltol=1e-3 vabstol=1e-6 iabstol=1e-12 temp=27 \
  tnom=25 scalem=1.0 scale=1.0 gmin=1e-12 rforce=1 maxnotes=5 maxwarns=5 \
  digits=5 cols=80 pivrel=1e-3 sensfile="./psf/sens.output" \
  checklimitdest=psf
tran tran stop=10n write="spectre.ic" writefinal="spectre.fc" \
  annotate=status maxiters=5
finalTimeOP info what=oppoint where=rawfile
modelParameter info what=models where=rawfile
element info what=inst where=rawfile
outputParameter info what=output where=rawfile
designParamVals info what=parameters where=rawfile
primitives info what=primitives where=rawfile
subckts info what=subckts where=rawfile
saveOptions options save=allpub
//////////////////////////////////End of charge scaling DAC//////////////////////////////////

```

```

// Generated for: spectre
// Generated on: May 24 11:20:13 2012
// Design library name: charge_measurement
// Design cell name: 4bit_sync_counter
// Design view name: schematic
simulator lang=spectre
global 0
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_rvtp9_v041.lib.scs"
section=ff

```

```

//////////////////////////////////Beginning of 4-bit counter//////////////////////////////////
// Library name: charge_measurement
// Cell name: inverter
// View name: schematic
subckt inverter in out vdd vss
  PM0 (out in vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (out in vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends inverter
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: nand
// View name: schematic
subckt nand a b out vdd vss
  PM1 (out b vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (out a vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (net14 b vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM1 (out a net14 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends nand
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: nand3
// View name: schematic
subckt nand3 a b c out vdd vss
  NM2 (net7 c vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM1 (out a net15 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (net15 b net7 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM2 (out a vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (out b vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM1 (out c vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends nand3
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: Tff_clear

```



```

// View name: schematic
subckt Tff_clear Q Q0 T clear clock vdd vss
  I10 (clock clockb vdd vss) inverter
  I8 (net24 Q0 Q vdd vss) nand
  I7 (clockb net27 net19 vdd vss) nand
  I6 (net40 clockb net24 vdd vss) nand
  I4 (net53 net27 net40 vdd vss) nand
  I9 (Q net19 clear Q0 vdd vss) nand3
  I5 (net40 net47 clear net27 vdd vss) nand3
  I3 (T clock Q net47 vdd vss) nand3
  I2 (Q0 clock T net53 vdd vss) nand3
ends Tff_clear
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: 4bit_sync_counter
// View name: schematic
I12 (net10 net11 vdd vss) inverter
I10 (net14 net45 vdd vss) inverter
I7 (net34 net19 vdd vss) inverter
I13 (out2 net45 net10 vdd vss) nand
I11 (out1 net19 net14 vdd vss) nand
I4 (enable_high out0 net34 vdd vss) nand
I3 (out3 net39 net11 clear_activelow clock vdd vss) Tff_clear
I2 (out2 net46 net45 clear_activelow clock vdd vss) Tff_clear
I1 (out1 net53 net19 clear_activelow clock vdd vss) Tff_clear
I0 (out0 net60 enable_high clear_activelow clock vdd vss) Tff_clear
include "./_graphical_stimuli.scs"
simulatorOptions options reltol=1e-3 vabstol=1e-6 iabstol=1e-12 temp=27 \
  tnom=25 scalem=1.0 scale=1.0 gmin=1e-12 rforce=1 maxnotes=5 maxwarns=5 \
  digits=5 cols=80 pivrel=1e-3 sensfile="./psf/sens.output" \
  checklimitdest=psf
tran tran stop=16n write="spectre.ic" writefinal="spectre.fc" \
  annotate=status maxiters=5
finalTimeOP info what=oppoint where=rawfile
modelParameter info what=models where=rawfile
element info what=inst where=rawfile
outputParameter info what=output where=rawfile
designParamVals info what=parameters where=rawfile
primitives info what=primitives where=rawfile
subckts info what=subckts where=rawfile
saveOptions options save=allpub
//////////////////////////////////End of charge scaling DAC//////////////////////////////////

// Generated for: spectre
// Generated on: Jun 24 15:48:35 2012

```

```
// Design library name: charge_measurement
// Design cell name: PeakDetector
// Design view name: schematic
simulator lang=spectre
global 0
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_hvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_lvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_rvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40_momcaps_v041.lib.scs"
section=tt
```

//////////////////////////////////**Beginning of peak detector**//////////////////////////////////

```
// Library name: charge_measurement
// Cell name: PeakDetector
// View name: schematic
PM2 (vout net0121 vdd vdd) p_p9_ghvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
PM3 (net0121 net0121 vdd vdd) p_p9_ghvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
NM2 (vout vreset vss vss) n_p9_ghvt m=1 mf=1 w=200n l=40n nf=1 ad=26f \
as=26f pd=660n ps=660n sa=130n sb=130n sd=0 mis_flag=1 sca=178.571 \
scb=34.6615m scc=14.4428m
C0 (vout vss vss) momcaps_sy_mmkf l=5u nf=10 nm=3 bm=1 m=9 mis_flag=1 \
metal_ring_flag=1 shielding_flag=0 presim_flag=1
NM0 (net13 vpeak vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
NM1 (net17 vout vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
NM5 (net21 net25 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
NM4 (net25 net25 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
NM6 (net0121 net21 vss vss) n_p9_grvt m=1 mf=1 w=400n l=230n nf=1 ad=52f \
```

```

as=52f pd=1.06u ps=1.06u sa=130n sb=130n sd=0 mis_flag=1 \
sca=104.167 scb=31.5004m scc=9.51325m
PM0 (net13 net13 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
PM1 (net17 net13 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
PM5 (net21 vout vdd vdd) p_p9_grvt m=1 mf=1 w=1u l=230n nf=1 ad=130f \
as=130f pd=2.26u ps=2.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=46.2963 scb=18.1908m scc=4.04276m
PM4 (net25 vpeak vdd vdd) p_p9_grvt m=1 mf=1 w=1u l=230n nf=1 ad=130f \
as=130f pd=2.26u ps=2.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=46.2963 scb=18.1908m scc=4.04276m
PM6 (net0121 net17 vdd vdd) p_p9_grvt m=3 mf=3 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
include "./_graphical_stimuli.scs"
simulatorOptions options reitol=1e-3 vabstol=1e-6 iabstol=1e-12 temp=27 \
tnom=25 scalem=1.0 scale=1.0 gmin=1e-12 rforce=1 maxnotes=5 maxwarns=5 \
digits=5 cols=80 pivrel=1e-3 sensfile="./psf/sens.output" \
checklimitdest=psf
tran tran stop=400n write="spectre.ic" writefinal="spectre.fc" \
annotate=status maxiters=5
finalTimeOP info what=oppoint where=rawfile
modelParameter info what=models where=rawfile
element info what=inst where=rawfile
outputParameter info what=output where=rawfile
designParamVals info what=parameters where=rawfile
primitives info what=primitives where=rawfile
subckts info what=subckts where=rawfile
saveOptions options save=allpub
//////////////////////////////////End of peak detector//////////////////////////////////

// Generated for: spectre
// Generated on: Jun 17 13:22:00 2012
// Design library name: charge_measurement
// Design cell name: comparator
// Design view name: schematic
simulator lang=spectre
global 0
parameters vdiff=0
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/140g_rvtp9_v041.lib.scs"
section=tt

```

```
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_io2p5_v021.lib.scs"
section=tt
```

```
//////////////////////////////////Beginning of comparator//////////////////////////////////
```

```
// Library name: charge_measurement
```

```
// Cell name: comparator
```

```
// View name: schematic
```

```
PM7 (out out2 vdd vdd) p_p9_grvt m=3 mf=3 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
PM4 (net28 vp vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=230n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
```

```
PM5 (out1 vn vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=230n nf=1 ad=195f \
as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=31.6456 scb=12.4686m scc=2.69597m
```

```
PM1 (out2 net40 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
PM0 (net40 net40 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
NM7 (out out1 vss vss) n_p9_grvt m=1 mf=1 w=400n l=230n nf=1 ad=52f as=52f \
pd=1.06u ps=1.06u sa=130n sb=130n sd=0 mis_flag=1 sca=104.167 \
scb=31.5004m scc=9.51325m
```

```
NM4 (net28 net28 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
NM5 (out1 net28 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
NM1 (out2 vn vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
NM0 (net40 vp vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
sca=68.0272 scb=25.0363m scc=6.13303m
```

```
include "./_graphical_stimuli.scs"
```

```
simulatorOptions options reitol=1e-3 vabstol=1e-6 iabstol=1e-12 temp=27 \
tnom=25 scalem=1.0 scale=1.0 gmin=1e-12 rforce=1 maxnotes=5 maxwarns=5 \
digits=5 cols=80 pivrel=1e-3 sensfile="./psf/sens.output" \
checklimitdest=psf
```

```
tran tran stop=20n write="spectre.ic" writefinal="spectre.fc" \
annotate=status maxiters=5
```

```
finalTimeOP info what=oppoint where=rawfile
```

```

modelParameter info what=models where=rawfile
element info what=inst where=rawfile
outputParameter info what=output where=rawfile
designParamVals info what=parameters where=rawfile
primitives info what=primitives where=rawfile
subckts info what=subckts where=rawfile
saveOptions options save=allpub
//////////////////////////////////End of comparator//////////////////////////////////

```

```

// Generated for: spectre
// Generated on: Jun 22 15:58:08 2012
// Design library name: charge_measurement
// Design cell name: measurementckt
// Design view name: schematic
simulator lang=spectre
global 0
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_hvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_rvtp9_v041.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40g_io2p5_v021.lib.scs"
section=tt
include
"/usr/local/isde/PDK/UMC/FDK/FDK001/umc40ge/./Models/Spectre/l40_momcaps_v041.lib.scs"
section=tt

```

```

//////////////////////////////////Beginning of measurement circuit//////////////////////////////////

```

```

// Library name: charge_measurement
// Cell name: comparator
// View name: schematic
subckt comparator out vdd vn vp vss
  PM7 (out out2 vdd vdd) p_p9_grvt m=3 mf=3 w=655n l=50n nf=1 ad=85.15f \
    as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=68.0272 scb=25.0363m scc=6.13303m
  PM4 (net28 vp vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=230n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM5 (out1 vn vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=230n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM1 (out2 net40 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
    ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
    mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m

```

```

PM0 (net40 net40 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
  ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
  mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM7 (out out1 vss vss) n_p9_grvt m=1 mf=1 w=400n l=230n nf=1 ad=52f \
  as=52f pd=1.06u ps=1.06u sa=130n sb=130n sd=0 mis_flag=1 \
  sca=104.167 scb=31.5004m scc=9.51325m
NM4 (net28 net28 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
  ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
  mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM5 (out1 net28 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
  ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
  mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM1 (out2 vn vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
  as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
  sca=68.0272 scb=25.0363m scc=6.13303m
NM0 (net40 vp vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 ad=85.15f \
  as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 mis_flag=1 \
  sca=68.0272 scb=25.0363m scc=6.13303m
ends comparator
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: inverter
// View name: schematic
subckt inverter in out vdd vss
  PM0 (out in vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (out in vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends inverter
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor_8
// View name: schematic
subckt multiplexor_8 in out vdd vss
  I0 (in inbar vdd vss) inverter
  PM1 (vdd inbar out vdd) p_p9_grvt m=8 mf=8 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
    as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
    sca=35.3357 scb=13.9568m scc=3.02914m
  NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \

```

```

    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
NM0 (out inbar vss vss) n_p9_grvt m=8 mf=8 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_8
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor_4
// View name: schematic
subckt multiplexor_4 in out vdd vss
    IO (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=4 mf=4 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
    PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
        as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
        sca=35.3357 scb=13.9568m scc=3.02914m
    NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out inbar vss vss) n_p9_grvt m=4 mf=4 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_4
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor_2
// View name: schematic
subckt multiplexor_2 in out vdd vss
    IO (in inbar vdd vss) inverter
    PM1 (vdd inbar out vdd) p_p9_grvt m=2 mf=2 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
    PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
        as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
        sca=35.3357 scb=13.9568m scc=3.02914m
    NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
    NM0 (out inbar vss vss) n_p9_grvt m=2 mf=2 w=1.5u l=40n nf=1 ad=195f \
        as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
        sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor_2

```

```

// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: multiplexor
// View name: schematic
subckt multiplexor in out vdd vss
  I0 (in inbar vdd vss) inverter
  PM1 (vdd inbar out vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (vss in out vdd) p_p9_grvt m=1 mf=1 w=4.005u l=40n nf=3 ad=360.45f \
    as=360.45f pd=5.88u ps=5.88u sa=130n sb=130n sd=140n mis_flag=1 \
    sca=35.3357 scb=13.9568m scc=3.02914m
  NM1 (out in vdd vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (out inbar vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends multiplexor
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: chargescalingDAC
// View name: schematic
subckt chargescalingDAC i0 i1 i2 i3 vdd vout vreset vss
  V0 (vactual vss) vsource type=pwl wave=[ 2.25n 0 2.75n 56m 3.25n \
    112.5m 3.75n 168m 4.25n 225m 4.75n 281.25m 5.25n 337.5m 5.75n \
    393.75m 6.25n 450m 6.75n 506.25m 7.25n 562.5m 7.75n 618.75m 8.25n \
    675m 8.75n 731.25m 9.25n 787.5m 9.75n 843.75m ]
  I0 (i3 net29 vdd vss) multiplexor_8
  I5 (i2 net25 vdd vss) multiplexor_4
  I10 (i1 net17 vdd vss) multiplexor_2
  C17 (vout net17 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=2 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
  C18 (vout net25 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=4 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
  C20 (vout net29 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=8 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
  C1 (vout net21 vss) momcaps_as_mmkf l=16.17u nf=13 nm=4 bm=1 m=1 \
    mis_flag=1 metal_ring_flag=1 presim_flag=1
  C0 (vout vss) capacitor c=50f
  NM0 (vout vreset vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  I6 (i0 net21 vdd vss) multiplexor

```



```

ends chargescalingDAC
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: nand
// View name: schematic
subckt nand a b out vdd vss
  PM1 (out b vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (out a vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM1 (out a net14 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (net14 b vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends nand
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: nand3
// View name: schematic
subckt nand3 a b c out vdd vss
  NM2 (net7 c vss vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM1 (out a net15 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM0 (net15 b net7 vss) n_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM2 (out a vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM0 (out b vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM1 (out c vdd vdd) p_p9_grvt m=1 mf=1 w=1.5u l=40n nf=1 ad=195f \
    as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
ends nand3
// End of subcircuit definition.

```

```

// Library name: charge_measurement
// Cell name: Tff_clear
// View name: schematic
subckt Tff_clear Q Q0 T clear clock vdd vss
  I10 (clock clockb vdd vss) inverter
  I8 (net24 Q0 Q vdd vss) nand
  I7 (clockb net27 net19 vdd vss) nand
  I6 (net40 clockb net24 vdd vss) nand
  I4 (net53 net27 net40 vdd vss) nand
  I9 (Q net19 clear Q0 vdd vss) nand3
  I5 (net40 net47 clear net27 vdd vss) nand3
  I3 (T clock Q net47 vdd vss) nand3
  I2 (Q0 clock T net53 vdd vss) nand3
ends Tff_clear
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: 4bit_sync_counter
// View name: schematic
subckt charge_measurement_4bit_sync_counter_schematic clear_activelow \
  clock enable_high out0 out1 out2 out3 vdd vss
  I12 (net10 net11 vdd vss) inverter
  I10 (net14 net45 vdd vss) inverter
  I7 (net34 net19 vdd vss) inverter
  I13 (out2 net45 net10 vdd vss) nand
  I11 (out1 net19 net14 vdd vss) nand
  I4 (enable_high out0 net34 vdd vss) nand
  I3 (out3 net39 net11 clear_activelow clock vdd vss) Tff_clear
  I2 (out2 net46 net45 clear_activelow clock vdd vss) Tff_clear
  I1 (out1 net53 net19 clear_activelow clock vdd vss) Tff_clear
  I0 (out0 net60 enable_high clear_activelow clock vdd vss) Tff_clear
ends charge_measurement_4bit_sync_counter_schematic
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: PeakDetector
// View name: schematic
subckt PeakDetector vdd vout vpeak vreset vss
  PM2 (vout net0121 vdd vdd) p_p9_ghvt m=1 mf=1 w=1.5u l=40n nf=1 \
    ad=195f as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  PM3 (net0121 net0121 vdd vdd) p_p9_ghvt m=1 mf=1 w=1.5u l=40n nf=1 \
    ad=195f as=195f pd=3.26u ps=3.26u sa=130n sb=130n sd=0 mis_flag=1 \
    sca=31.6456 scb=12.4686m scc=2.69597m
  NM2 (vout vreset vss vss) n_p9_ghvt m=1 mf=1 w=200n l=40n nf=1 ad=26f \

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as=26f pd=660n ps=660n sa=130n sb=130n sd=0 mis_flag=1 sca=178.571 \
scb=34.6615m scc=14.4428m
C0 (vout vss vss) momcaps_sy_mmkf l=5u nf=10 nm=3 bm=1 m=9 mis_flag=1 \
metal_ring_flag=1 shielding_flag=0 presim_flag=1
NM0 (net13 vpeak vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM1 (net17 vout vss vss) n_p9_grvt m=1 mf=1 w=655n l=230n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM5 (net21 net25 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM4 (net25 net25 vss vss) n_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
NM6 (net0121 net21 vss vss) n_p9_grvt m=1 mf=1 w=400n l=230n nf=1 \
ad=52f as=52f pd=1.06u ps=1.06u sa=130n sb=130n sd=0 mis_flag=1 \
sca=104.167 scb=31.5004m scc=9.51325m
PM0 (net13 net13 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
PM1 (net17 net13 vdd vdd) p_p9_grvt m=1 mf=1 w=655n l=50n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
PM5 (net21 vout vdd vdd) p_p9_grvt m=1 mf=1 w=1u l=230n nf=1 ad=130f \
as=130f pd=2.26u ps=2.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=46.2963 scb=18.1908m scc=4.04276m
PM4 (net25 vpeak vdd vdd) p_p9_grvt m=1 mf=1 w=1u l=230n nf=1 ad=130f \
as=130f pd=2.26u ps=2.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=46.2963 scb=18.1908m scc=4.04276m
PM6 (net0121 net17 vdd vdd) p_p9_grvt m=3 mf=3 w=655n l=50n nf=1 \
ad=85.15f as=85.15f pd=1.57u ps=1.57u sa=130n sb=130n sd=0 \
mis_flag=1 sca=68.0272 scb=25.0363m scc=6.13303m
ends PeakDetector
// End of subcircuit definition.

// Library name: charge_measurement
// Cell name: measurementckt
// View name: schematic
I7 (_3 vdd DAC_out PD_out vss) comparator
I5 (_3 _2 vdd vss) inverter
C0 (node vss vss) momcaps_sy_mmkf l=5u nf=10 nm=3 bm=1 m=9 mis_flag=1 \
metal_ring_flag=1 shielding_flag=0 presim_flag=1
PM0 (node vdd vdd vdd) p_2p5_g m=1 mf=1 w=1u l=270n nf=1 sa=170n sb=170n \
sd=0 mis_flag=1 ad=170f as=170f pd=2.34u ps=2.34u sca=14.9031 \

```

```

scb=13.6621m scc=1.77252m
I4 (vddhit node) isource type=pwl wave=[ 3n 0 3.05n 150u 3.21n 50u 3.4n \
50u 5.4n 0 ]
NM0 (node vreset vss vss) n_p9_grvt m=1 mf=1 w=2u l=40n nf=1 ad=260f \
as=260f pd=4.26u ps=4.26u sa=130n sb=130n sd=0 mis_flag=1 \
sca=24.0385 scb=9.38101m scc=2.02198m
I2 (o0 o1 o2 o3 vdd DAC_out vreset vss) chargescalingDAC
I1 (clear clock _2 o0 o1 o2 o3 vdd vss) \
charge_measurement_4bit_sync_counter_schematic
I0 (vdd PD_out node vreset vss) PeakDetector
include "../_graphical_stimuli.scs"
simulatorOptions options reltol=1e-3 vabstol=1e-6 iabstol=1e-12 temp=27 \
tnom=25 scalem=1.0 scale=1.0 gmin=1e-12 rforce=1 maxnotes=5 maxwarns=5 \
digits=5 cols=80 pivrel=1e-3 sensfile="./psf/sens.output" \
checklimitdest=psf
tran tran stop=16n write="spectre.ic" writefinal="spectre.fc" \
annotate=status maxiters=5
finalTimeOP info what=oppoint where=rawfile
modelParameter info what=models where=rawfile
element info what=inst where=rawfile
outputParameter info what=output where=rawfile
designParamVals info what=parameters where=rawfile
primitives info what=primitives where=rawfile
subckts info what=subckts where=rawfile
save I4:sink
saveOptions options save=allpub
//////////////////////////////////End of measurement circuit//////////////////////////////////

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